

# Nonlinear dispersive waves in acoustics

Vassos Achilleos

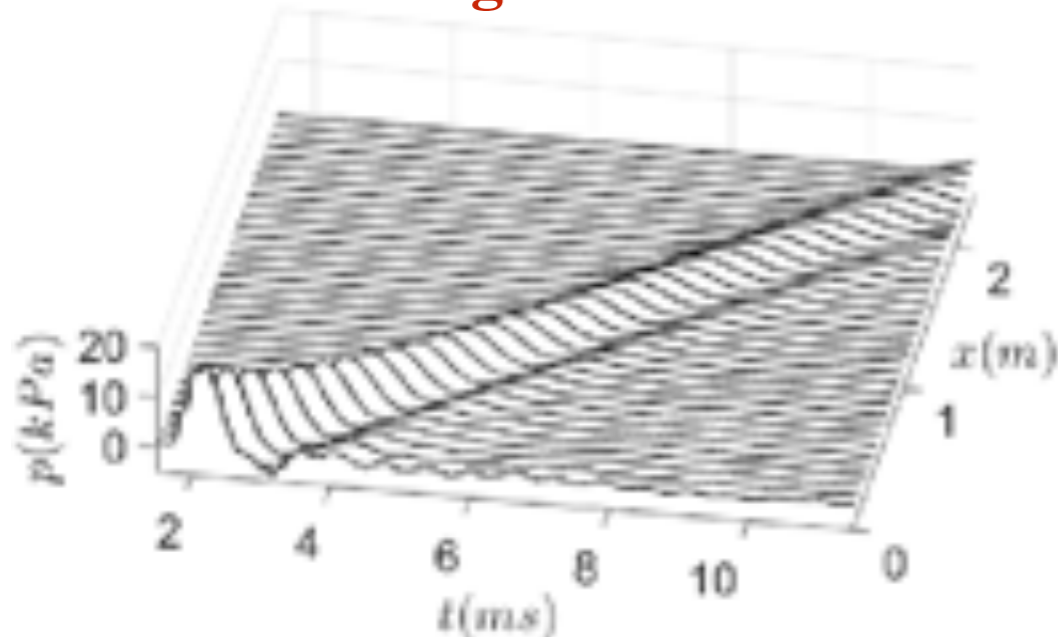
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- Laboratoire d'Acoustique de l'Université du Mans (LAUM), UMR 6613, Institut d'Acoustique - Graduate School (IA-GS), CNRS, Le Mans Université, France

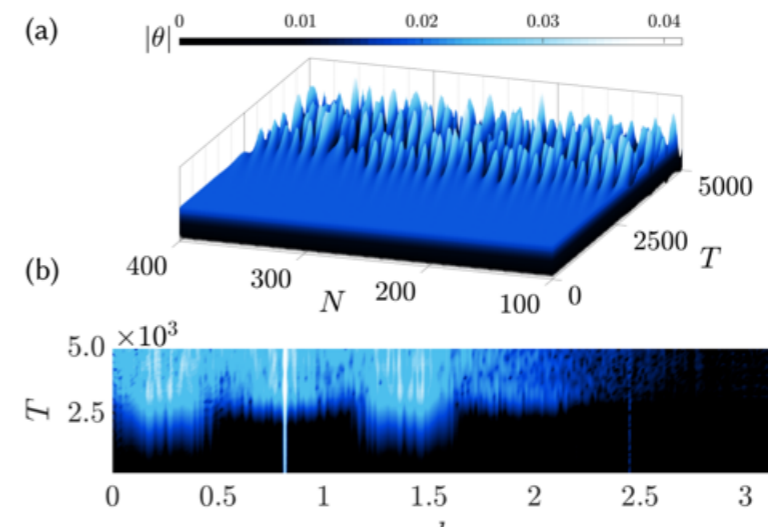
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**I. I. Sougleridis**



**A. Demiquel**



# Part 1: Solitons in airborne acoustics

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## Localised nonlinear waves in dispersive media

# Part 1: Solitons in airborne acoustics

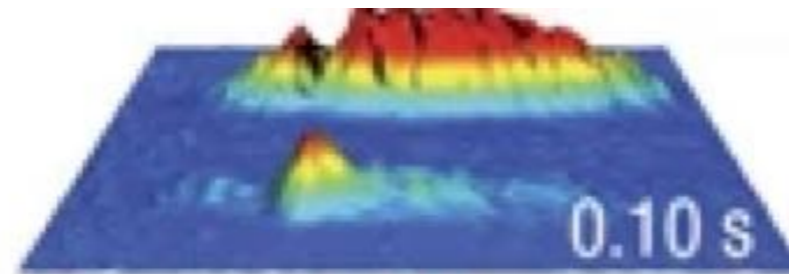
## Localised nonlinear waves in dispersive media

### Free water waves

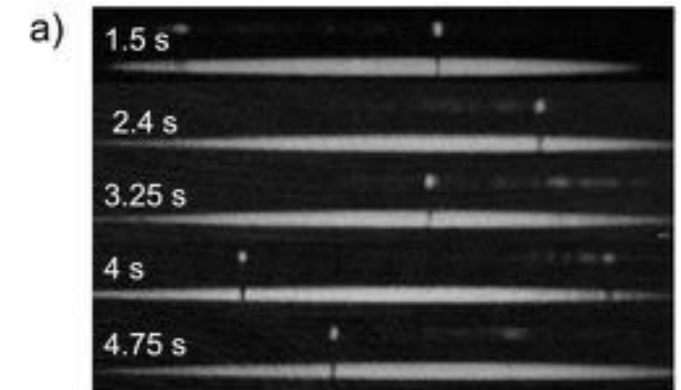


### Superfluids : Bose-Einstein Condensates

*Nature Physics* 4, 496–501 (2008)

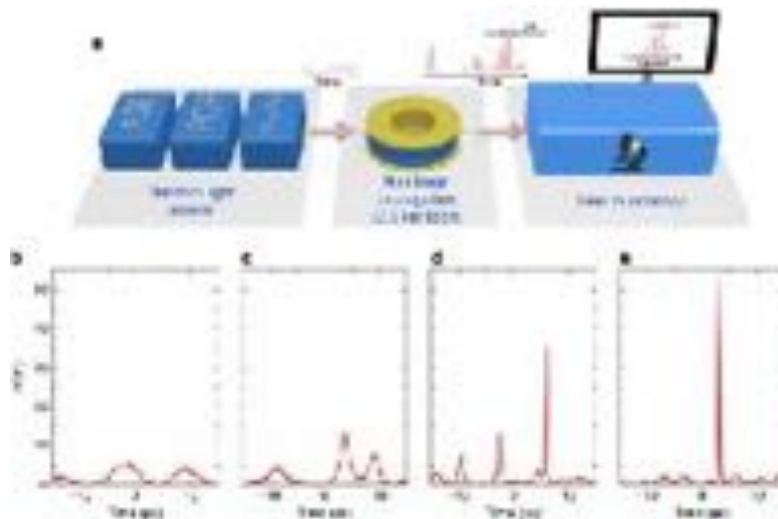


*Phys. Lett. A* 375 (2011) 642–646



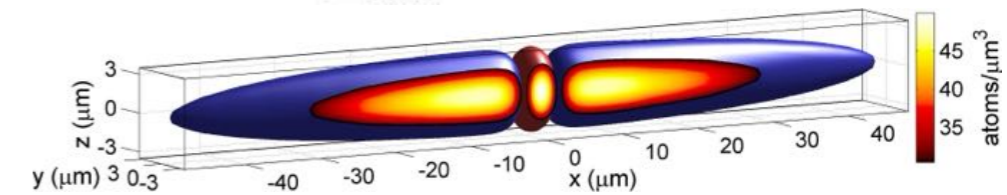
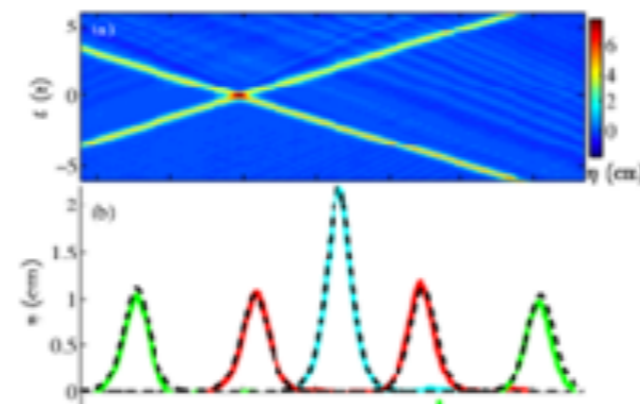
### Optical fibers

*Nature Communications*  
7, Article number: 13136 (2016)



### Water tanks

*Phys. Rev. Lett.* 122, 214502 (2019)



# Part 1: Solitons in airborne acoustics

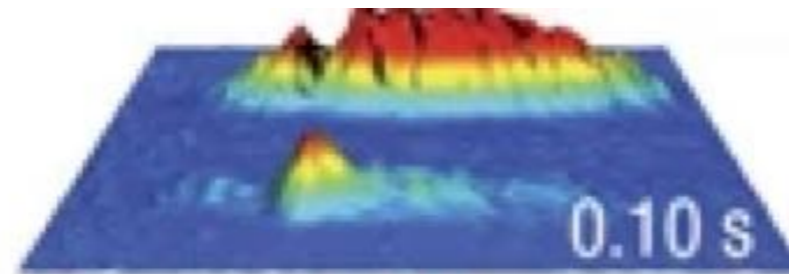
## Localised nonlinear waves in dispersive media

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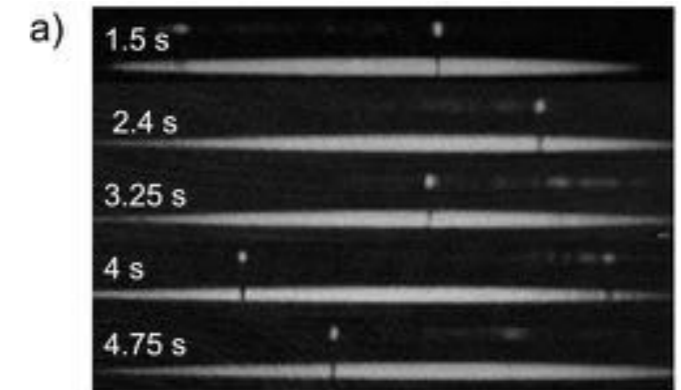


### Superfluids : Bose-Einstein Condensates

*Nature Physics* **4**, 496–501 (2008)

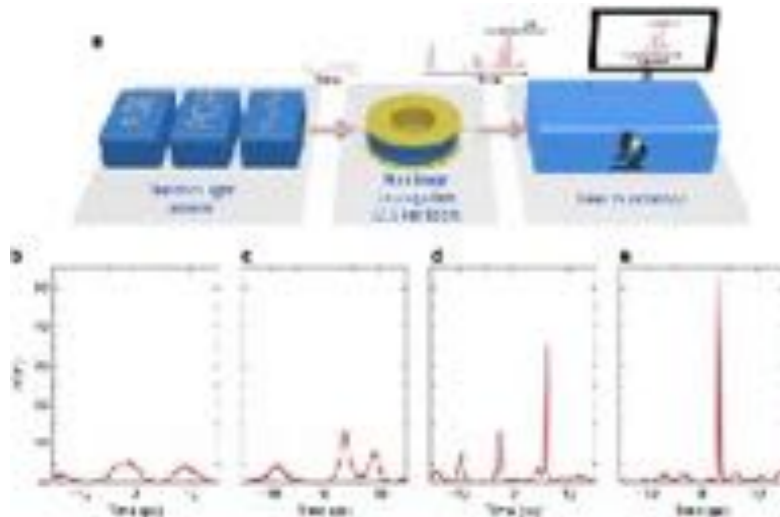


*Phys. Lett. A* **375** (2011) 642–646



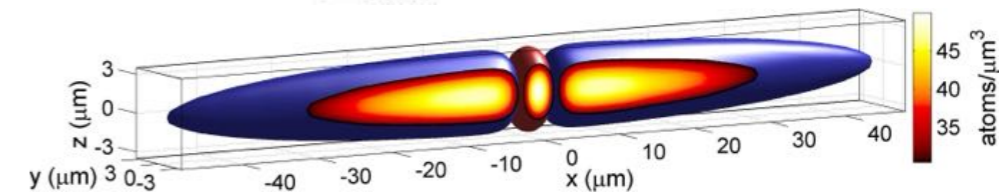
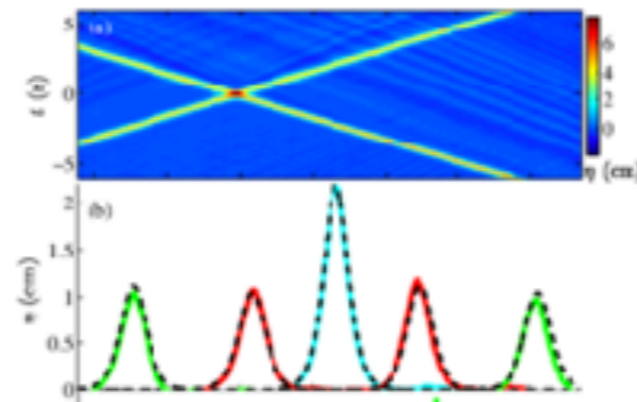
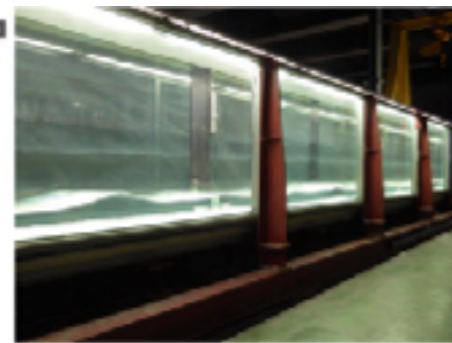
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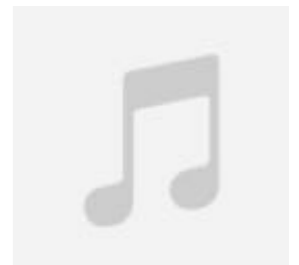
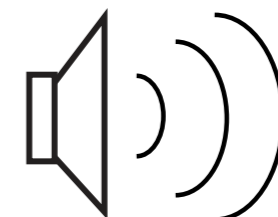


### Water tanks

*Phys. Rev. Lett.* **122**, 214502 (2019)



Why not in audible sound?



# Part 1: Solitons in airborne acoustics

*J. Fluid Mech.* (2004), vol. 504, pp. 271–299. © 2004 Cambridge University Press  
 DOI: 10.1017/S0022112004008109 Printed in the United Kingdom

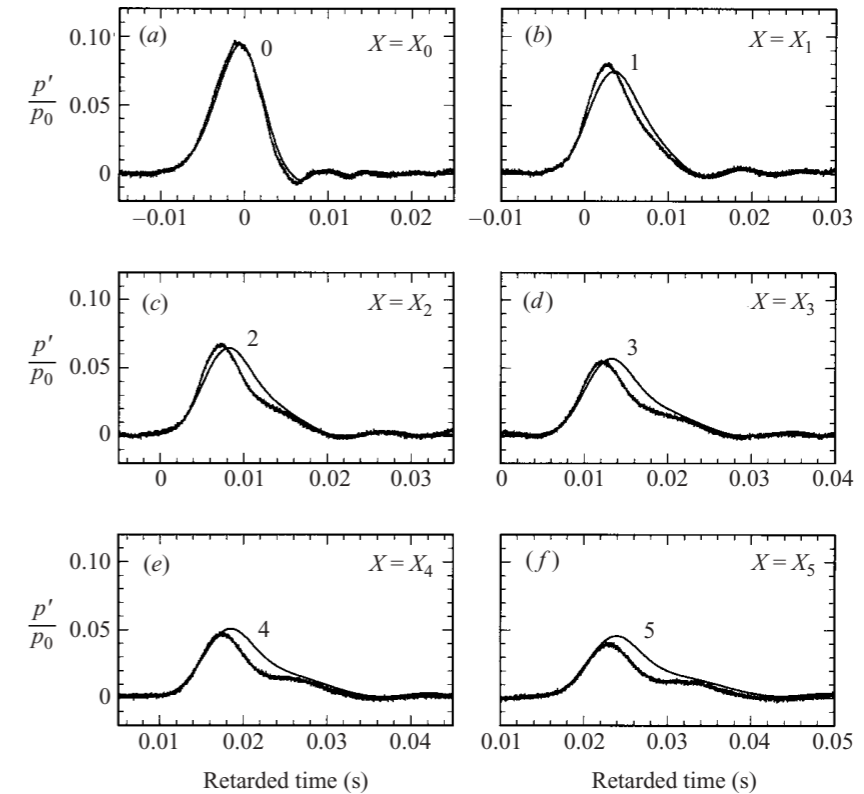
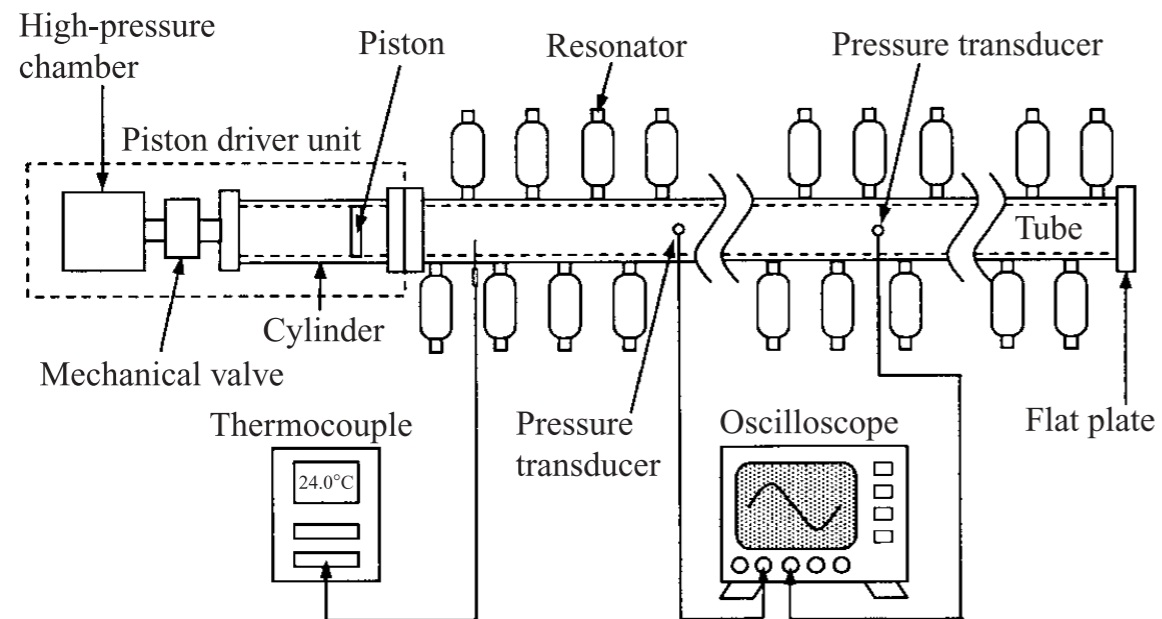
271

## Verification of acoustic solitary waves

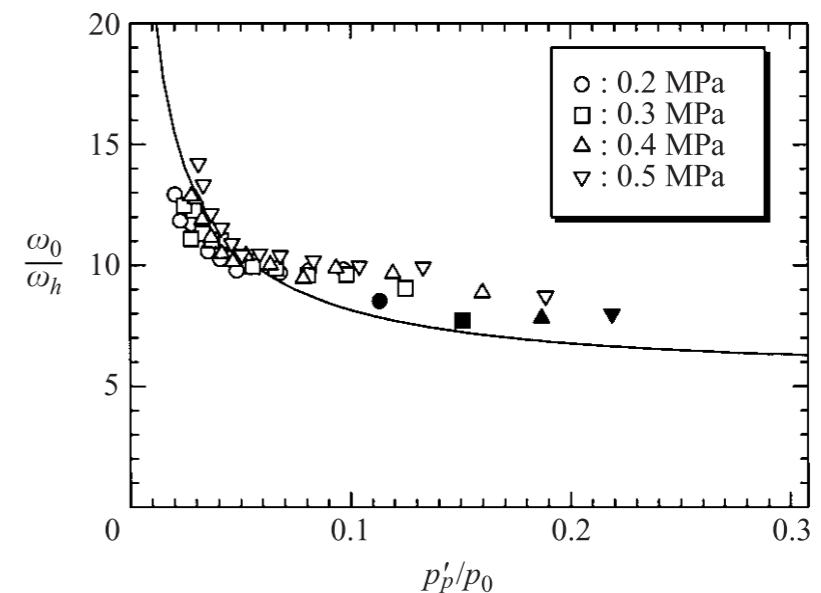
By N. SUGIMOTO, M. MASUDA, K. YAMASHITA  
 AND H. HORIMOTO

Division of Nonlinear Mechanics, Department of Mechanical Science, Graduate School of  
 Engineering Science, University of Osaka, Toyonaka, Osaka 560-8531, Japan

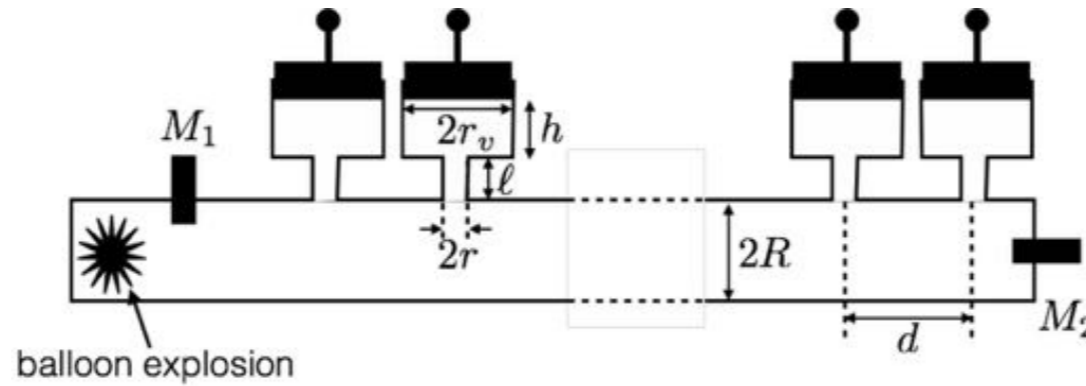
(Received 22 July 2003 and in revised form 18 November 2003)



## width of the soliton

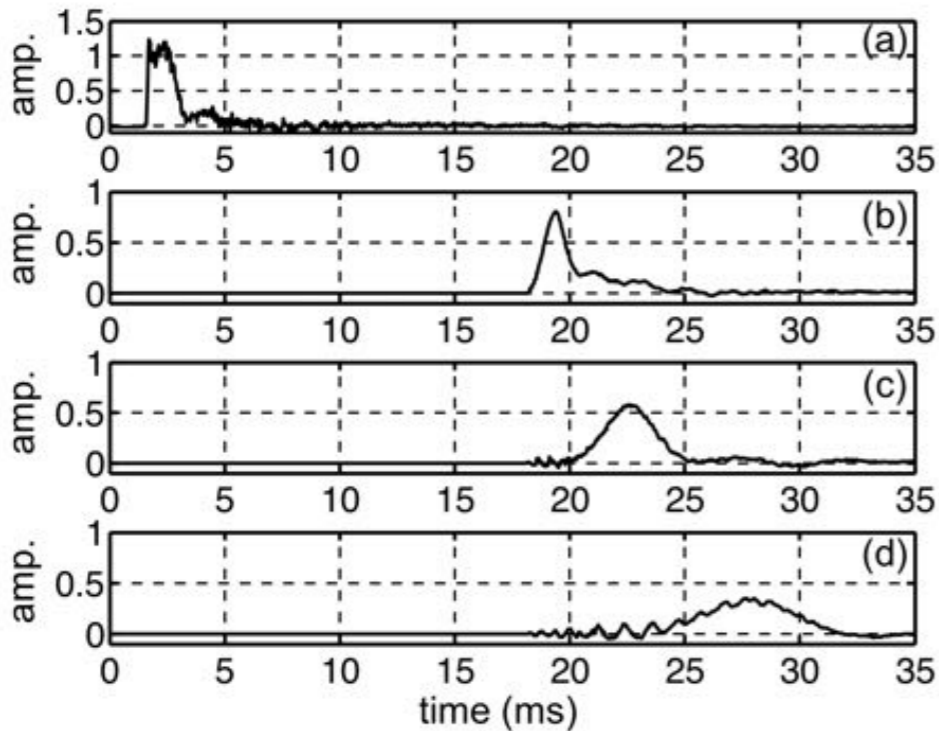
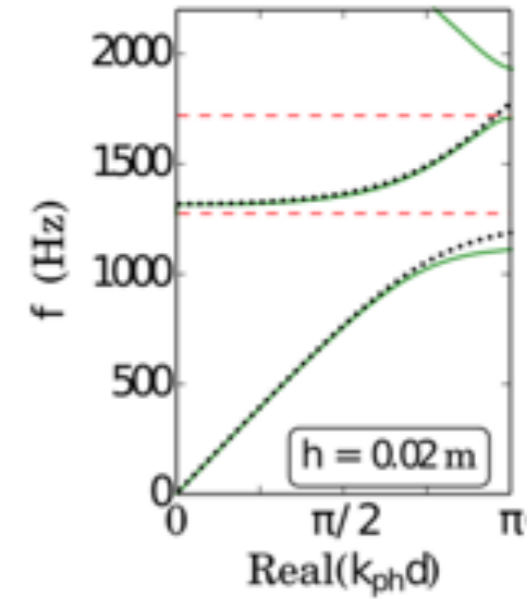


# Part 1: Solitons in airborne acoustics



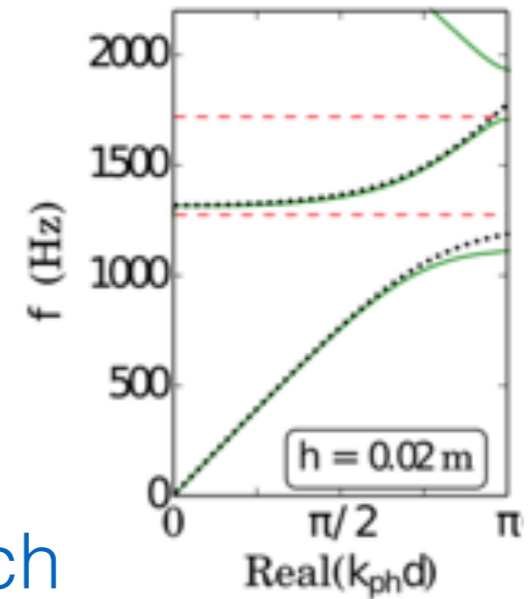
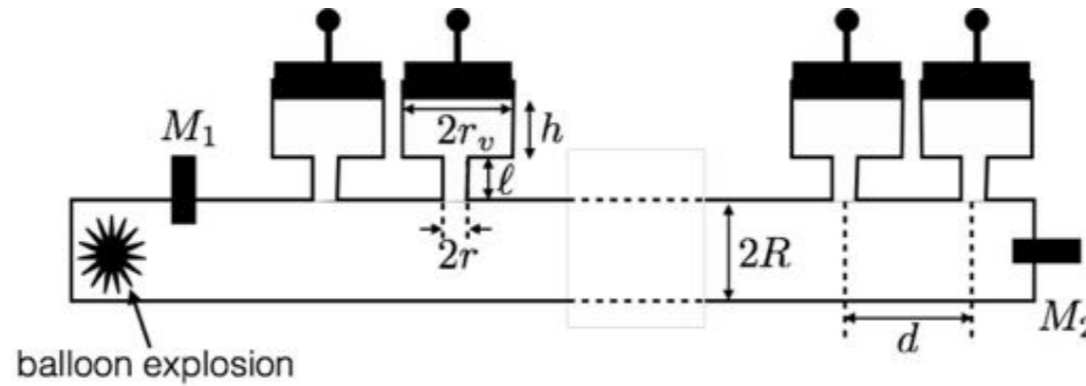
propagation velocity depends on particle velocity

$$\frac{dx}{dt} = c_0 + \beta u \quad \beta = 1 + \frac{B}{2A}$$



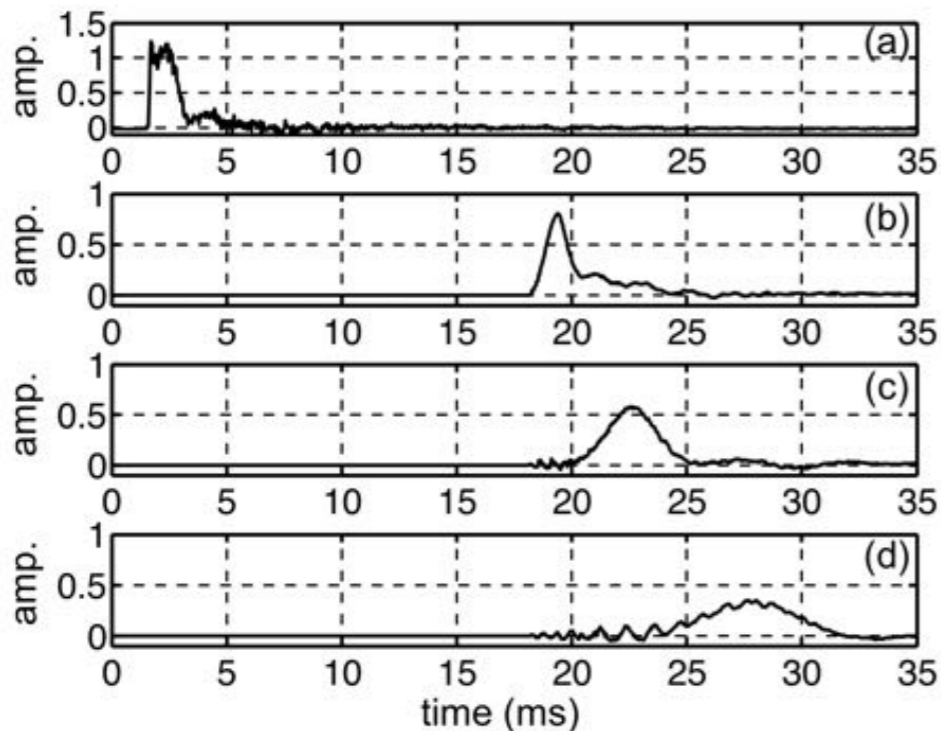
experiments

# Part 1: Solitons in airborne acoustics



## Electroacoustic analogue - Transmission line approach

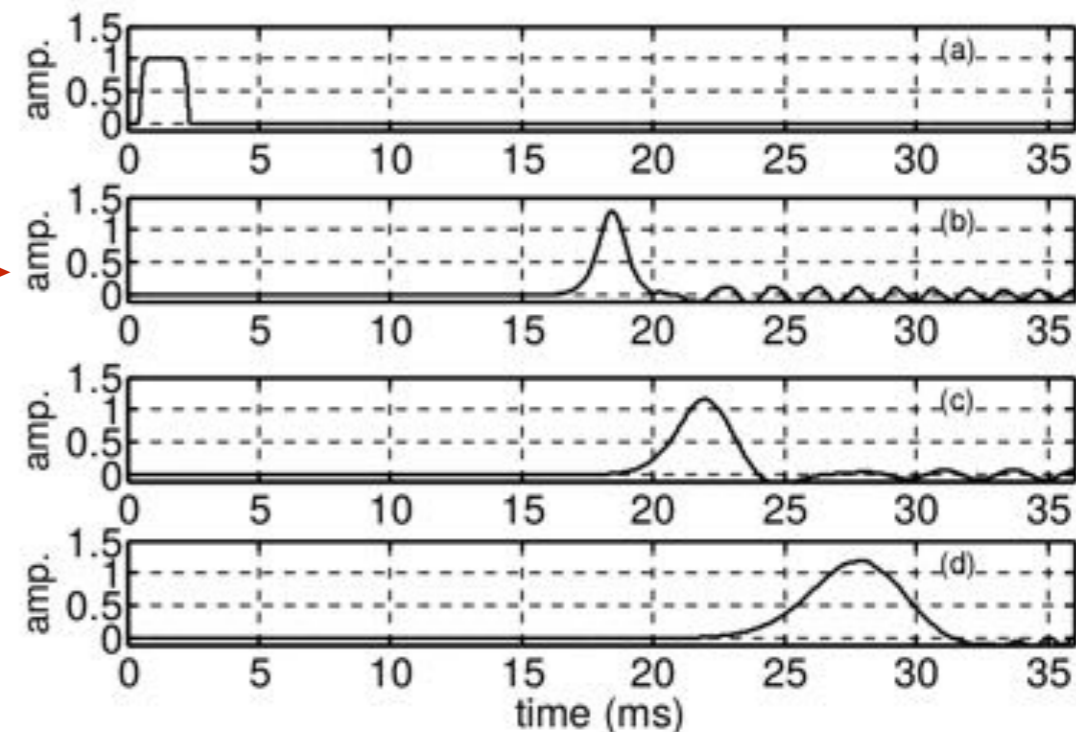
$$\frac{d^2 p_n}{dt^2} - \frac{c_0^2}{\kappa d^2} \left( 1 + \frac{1}{\omega_0^2} \frac{d^2}{dt^2} \right) \hat{\delta}^2 p_n + \frac{1}{\kappa} \frac{d^2}{dt^2} \left( 1 + \frac{1}{\omega_0^2} \frac{d^2}{dt^2} \right) \left[ p_n \left( 1 - 2 \frac{\beta_0}{\rho_0 c_0^2} p_n \right) \right] = 0$$



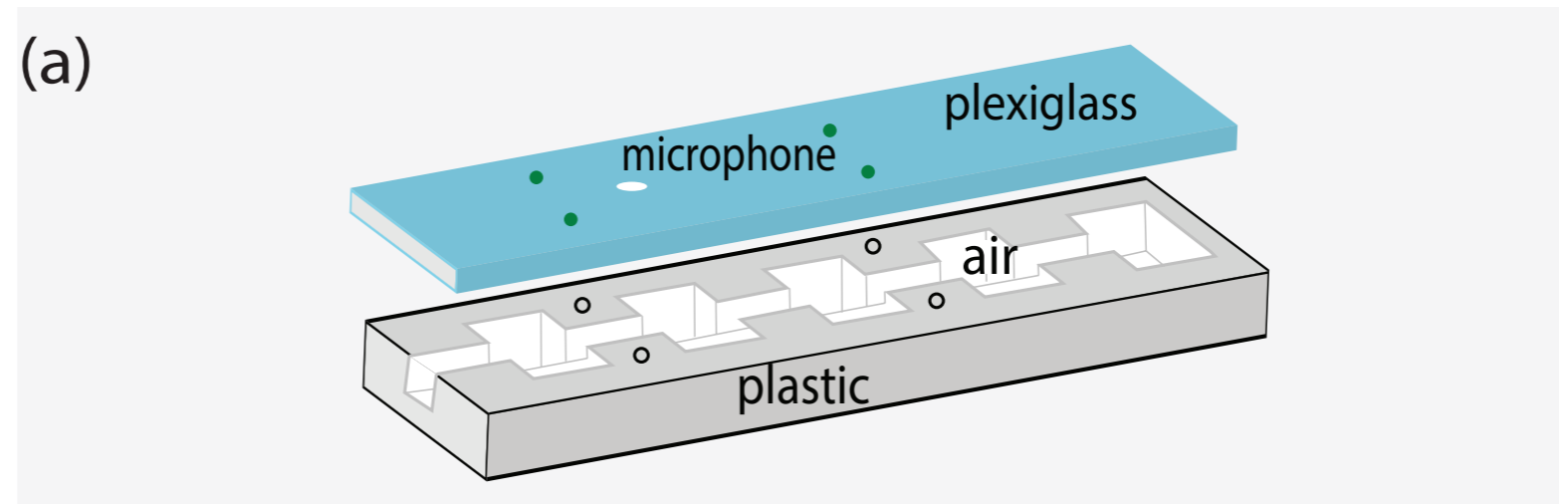
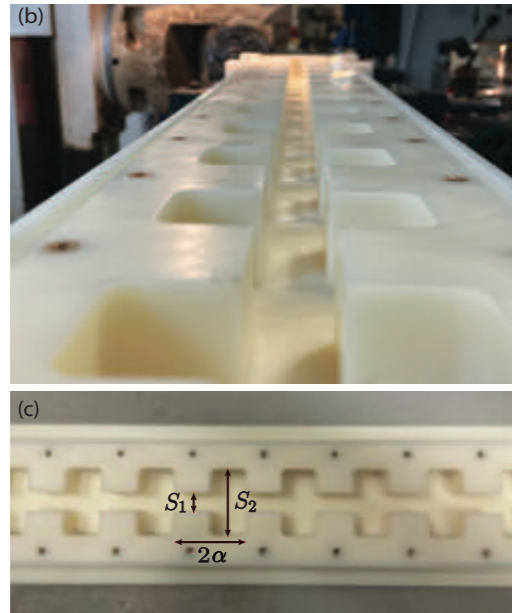
analogue



experiments

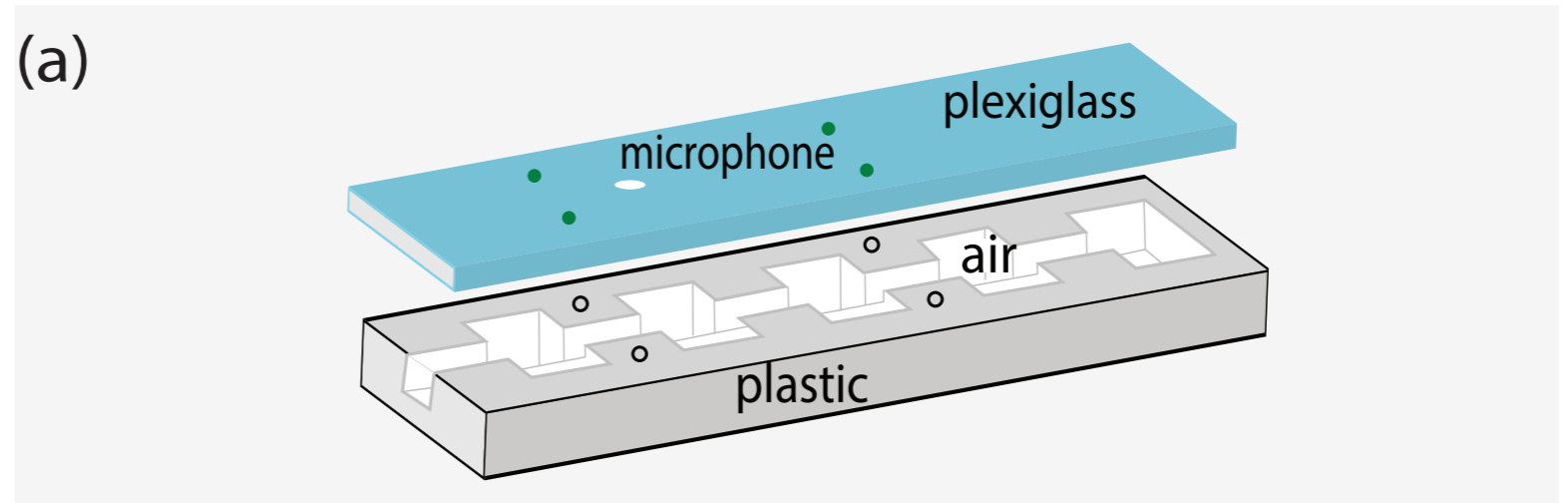
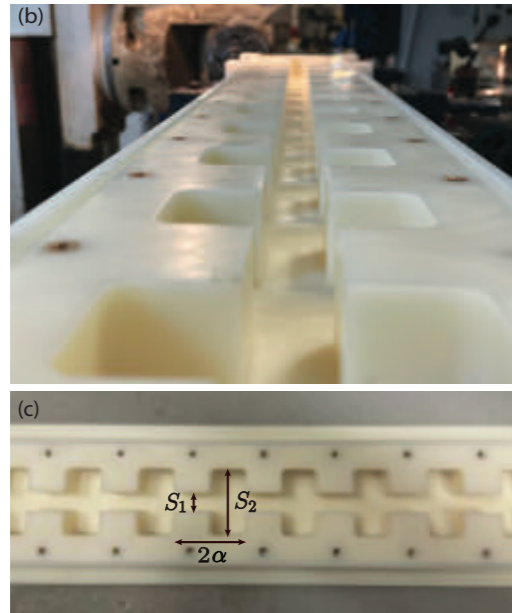


# Part 1: Solitons in airborne acoustics

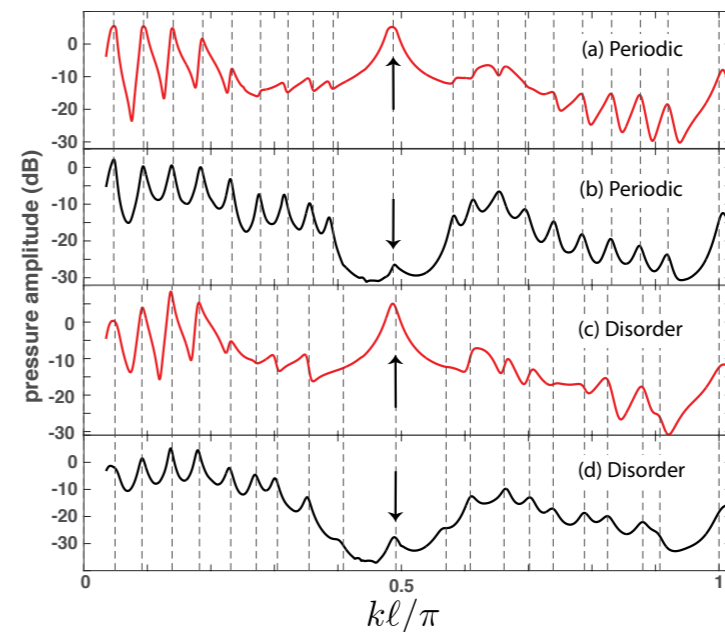
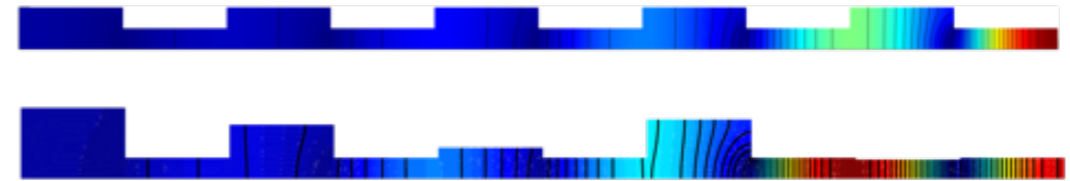
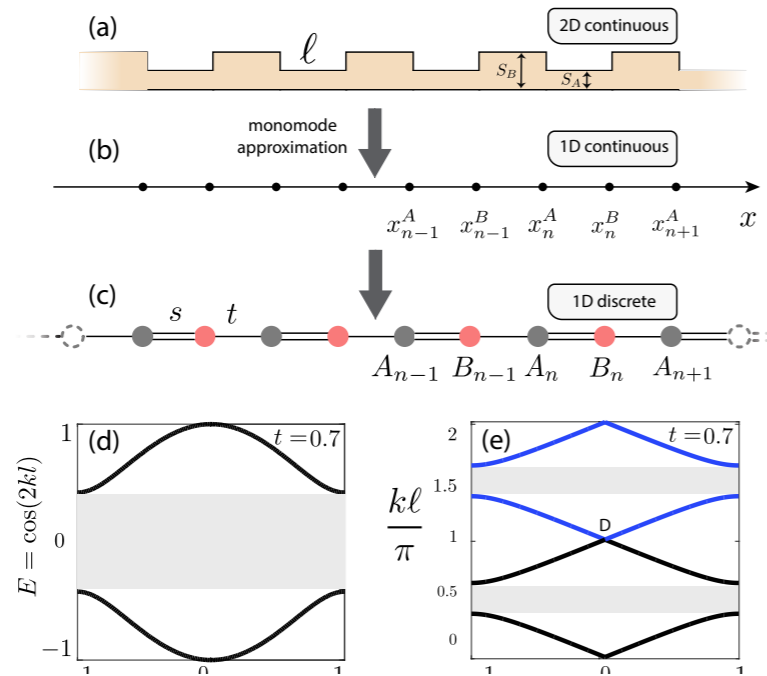




# Part 1: Solitons in airborne acoustics



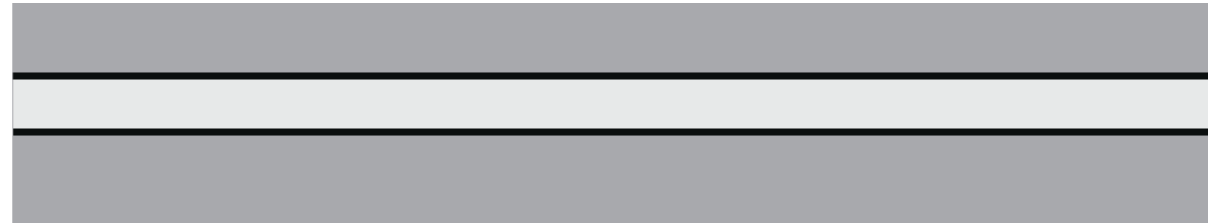
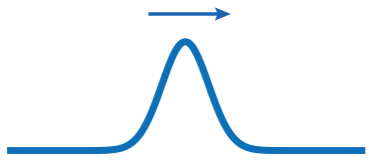
## Inspired by the topological SSH model in acoustics



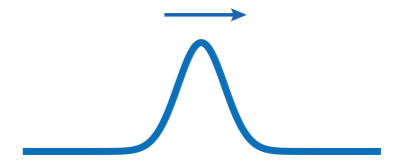
$$HX = EX$$

# Part 1: Solitons in airborne acoustics

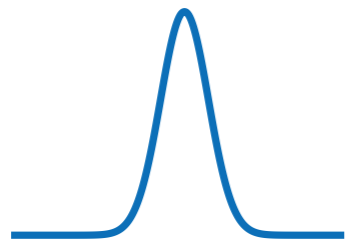
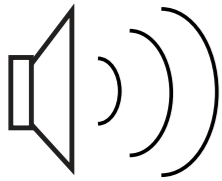
low amplitude



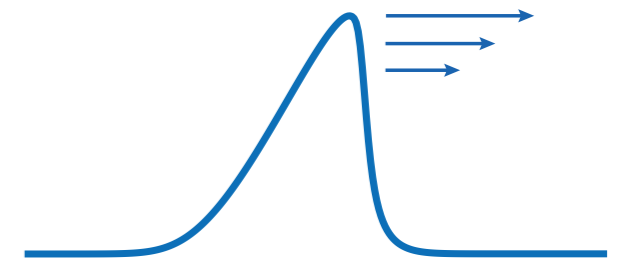
undistorted propagation



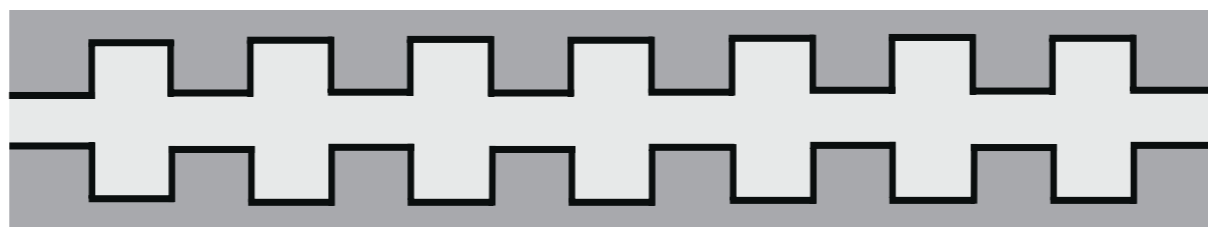
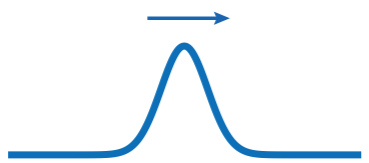
high amplitude



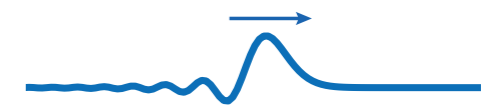
shock front formation



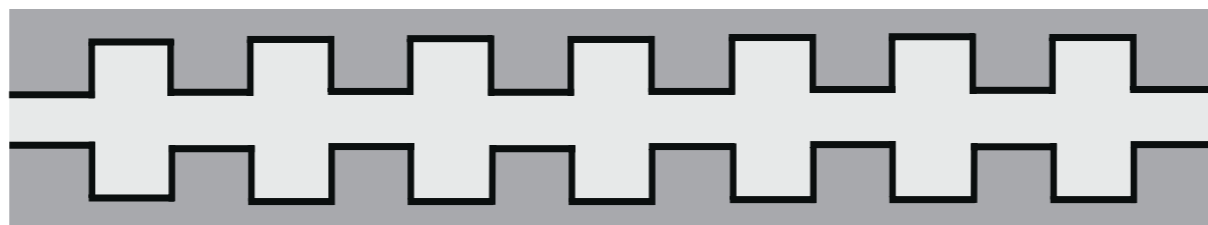
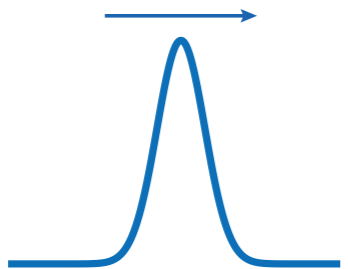
low amplitude



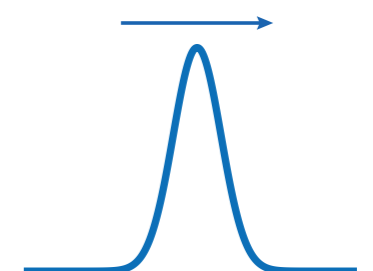
dispersion



high amplitude

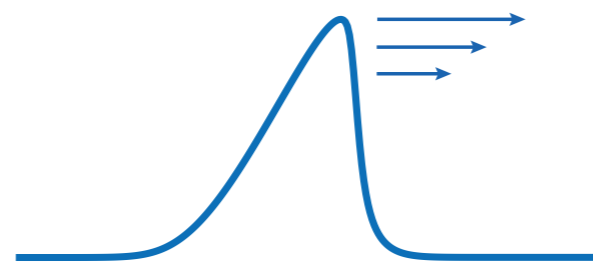


**soliton!**

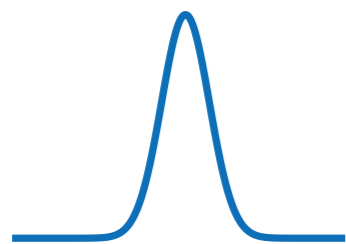
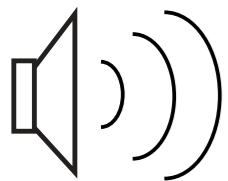


# Part 1: Solitons in airborne acoustics

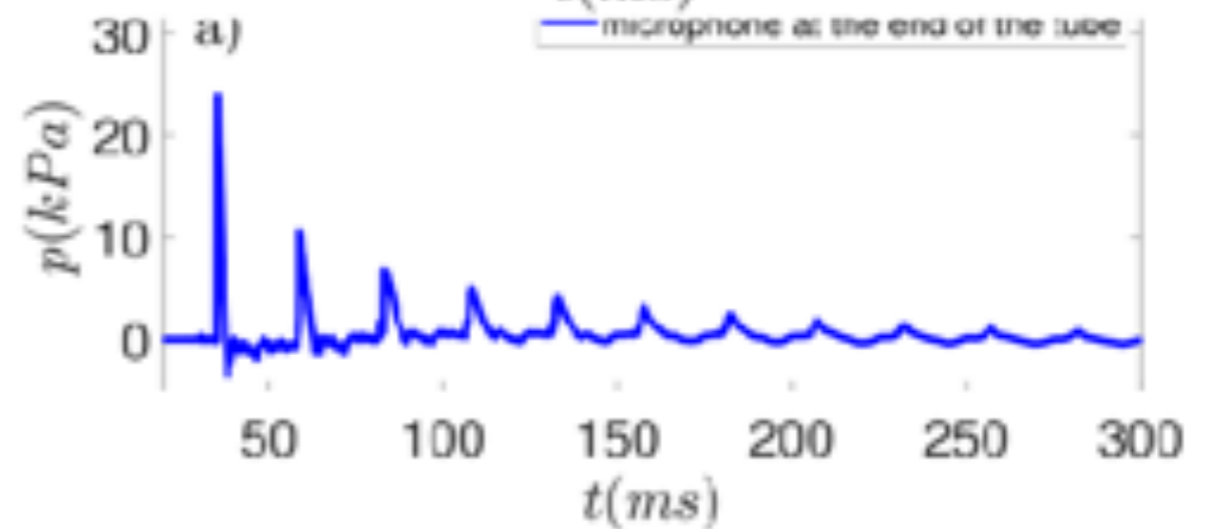
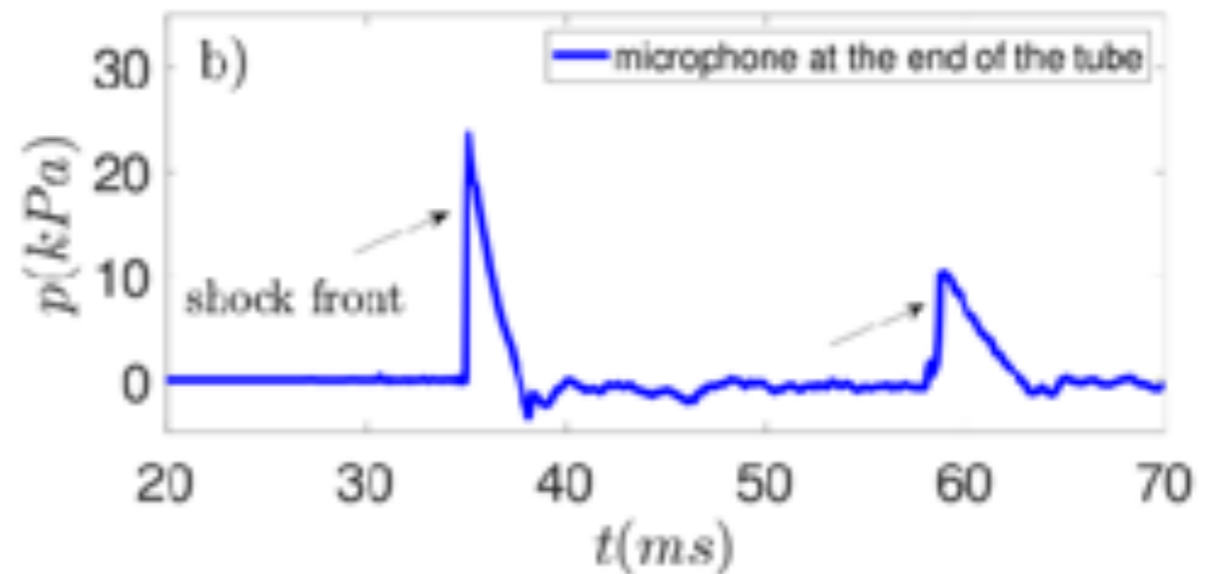
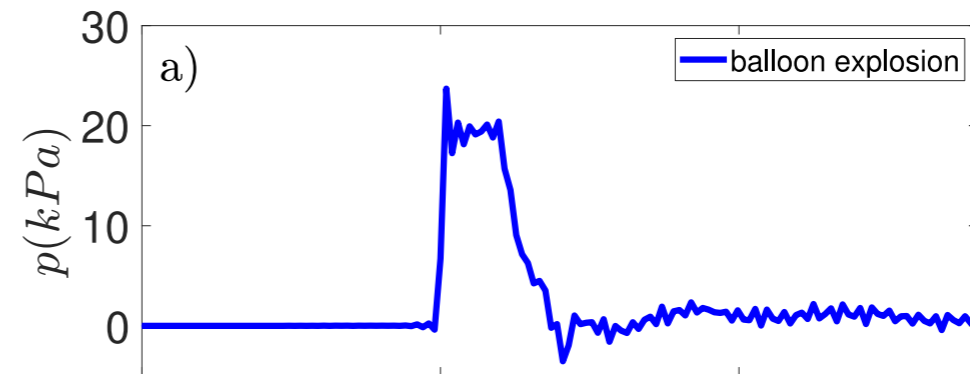
shock front formation



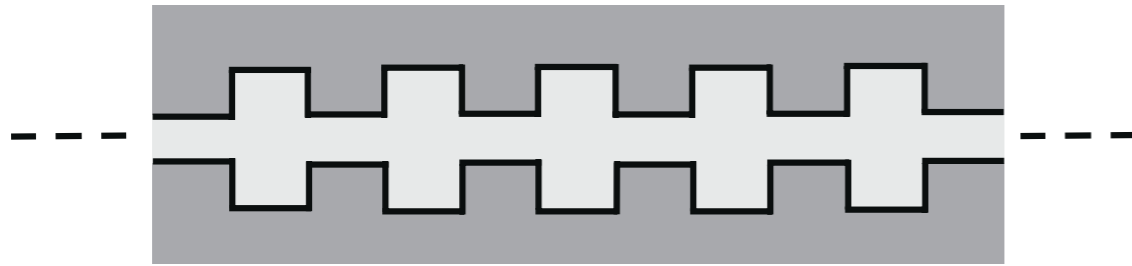
high amplitude



## Experimental measurements



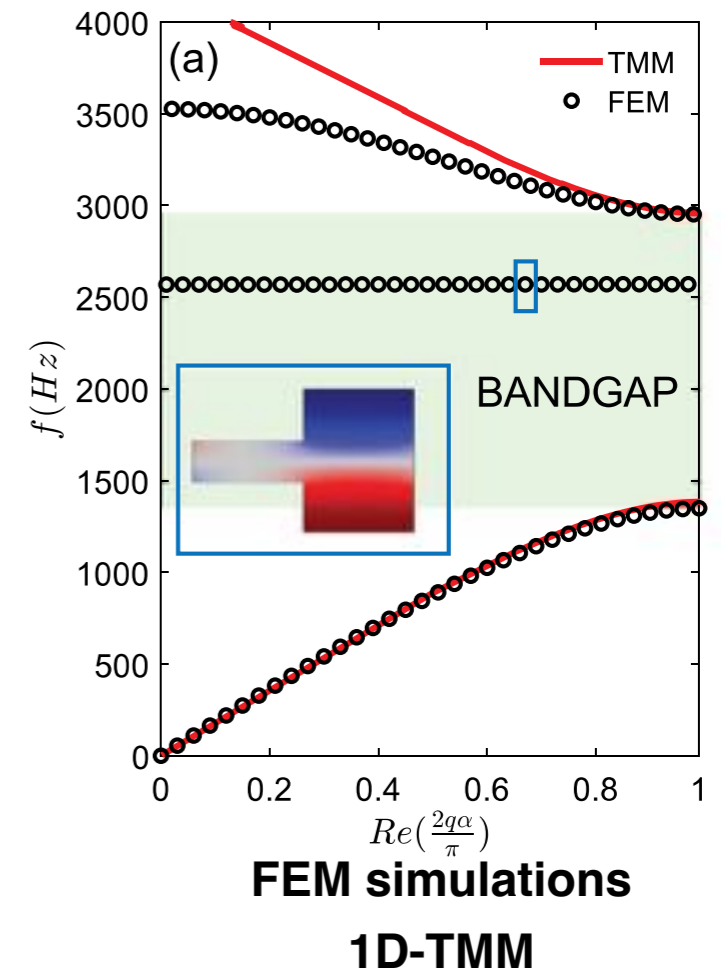
# Part 1: Solitons in airborne acoustics



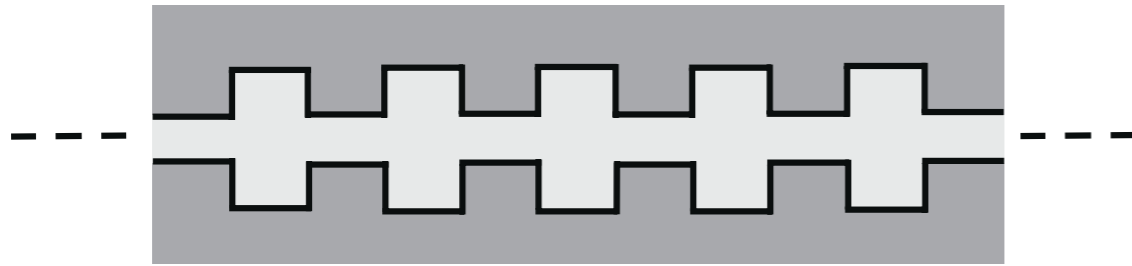
1-D approximation - Transfer matrix method

$$\cos(2q\alpha) = \cos^2(k\tilde{\alpha}) - \frac{S_1^2 + S_2^2}{2S_1S_2} \sin^2(k\tilde{\alpha})$$

$$\omega = ck$$



# Part 1: Solitons in airborne acoustics



1-D approximation - Transfer matrix method

$$\cos(2q\alpha) = \cos^2(k\tilde{\alpha}) - \frac{S_1^2 + S_2^2}{2S_1S_2} \sin^2(k\tilde{\alpha})$$

## Effective medium

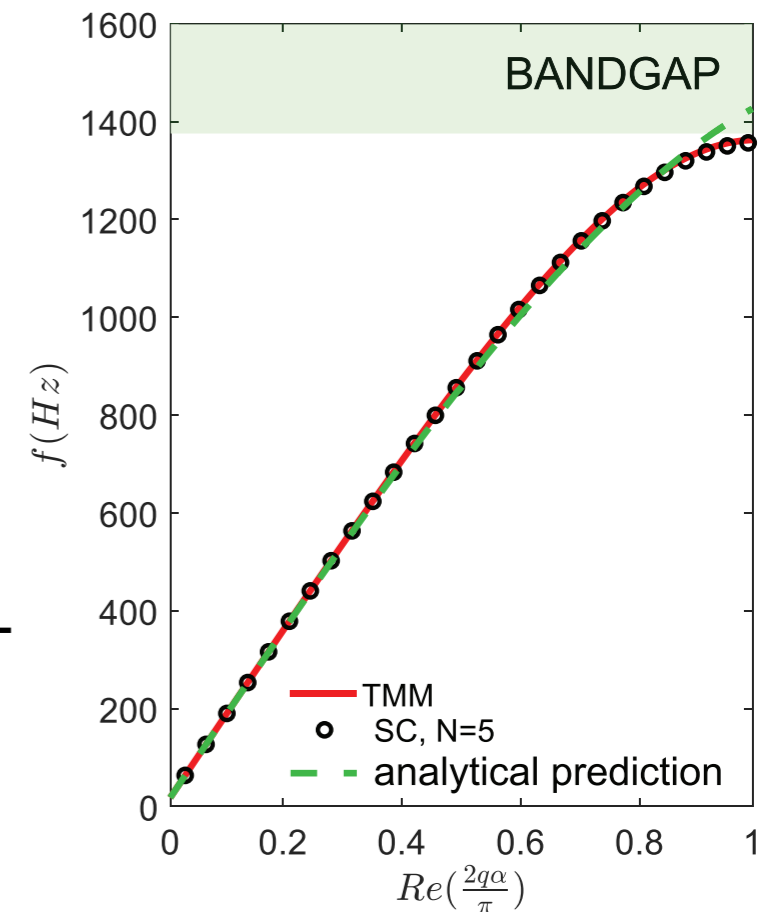


$$p_{tt} - b(p^2)_{tt} = \tilde{c}^2 p_{xx} + \beta_m p_{xxtt} + \beta_x p_{xxxx}$$

To find the coefficients we compare the two equations in the long wavelength limit

$$\omega\tilde{\alpha} = \tilde{c}_0 \left( q\alpha - \frac{\beta_m + \beta_x}{2} (q\alpha)^3 + \frac{(\beta_m + \beta_x)(3\beta_m - \beta_x)}{8} (q\alpha)^5 + O((q\alpha)^7) \right)$$

$$\omega\tilde{\alpha} = \tilde{c}_0 \left( q\alpha - \frac{\delta}{2} (q\alpha)^3 + 3\delta(Q - \delta)(q\alpha)^5 + O((q\alpha)^7) \right)$$



# Effective nonlinear PDE and the soliton solution

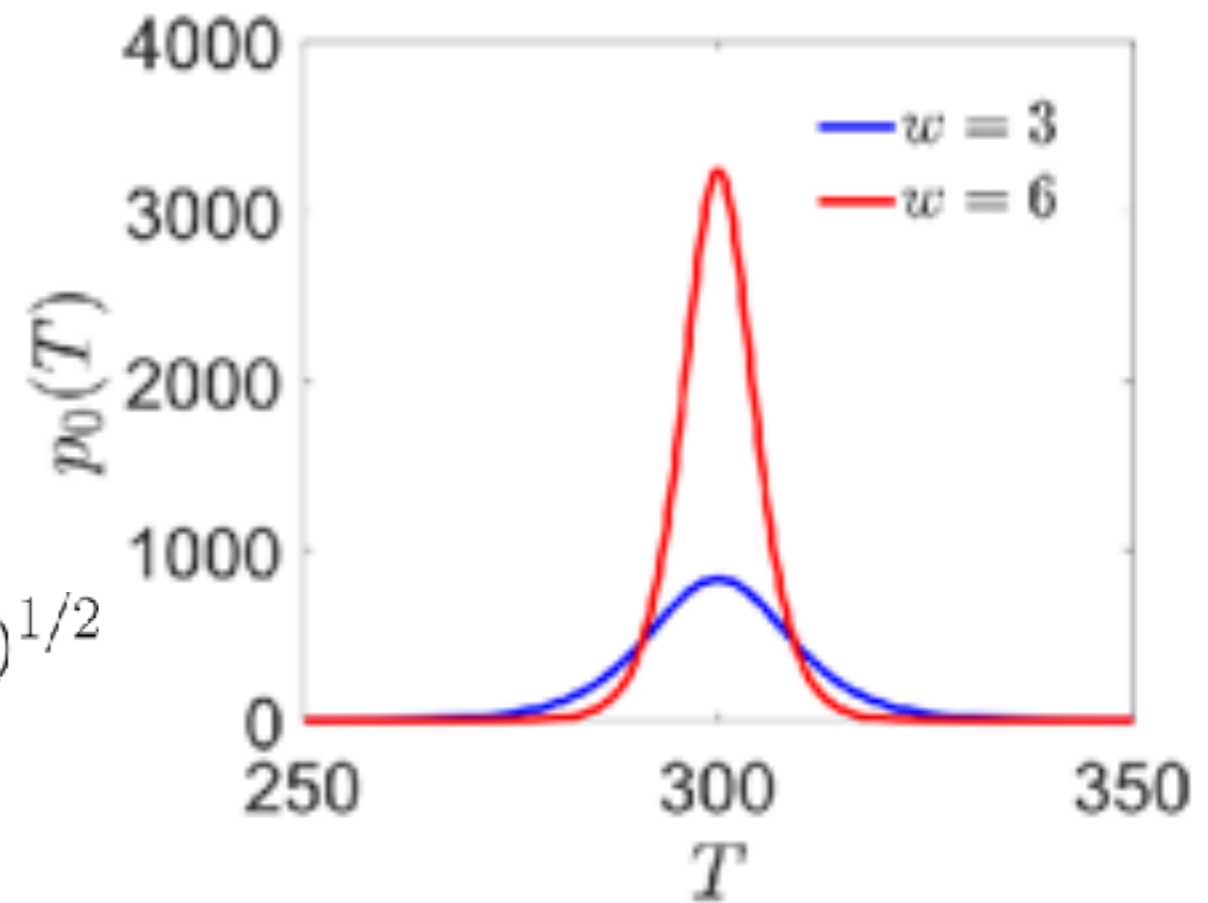
--- effective dispersive nonlinear medium ---

$$p_{tt} - b(p^2)_{tt} = \tilde{c}^2 p_{xx} + \beta_m p_{xxtt} + \beta_x p_{xxxx}$$

Soliton solutions (homoclinic orbits)

$$p(x, t) = A \operatorname{sech}^2 (w (x - \nu t))$$

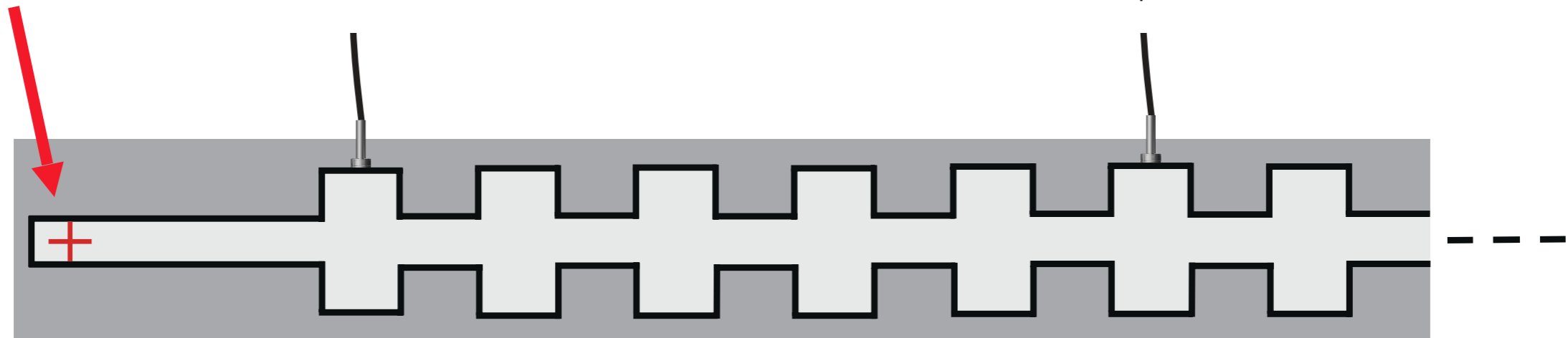
$$A = \frac{3(\nu^2 - \tilde{c}^2)}{2b\nu^2}, \quad w = ((\nu^2 - \tilde{c}^2)/4(\beta_x + \beta_m\nu^2))^{1/2}$$



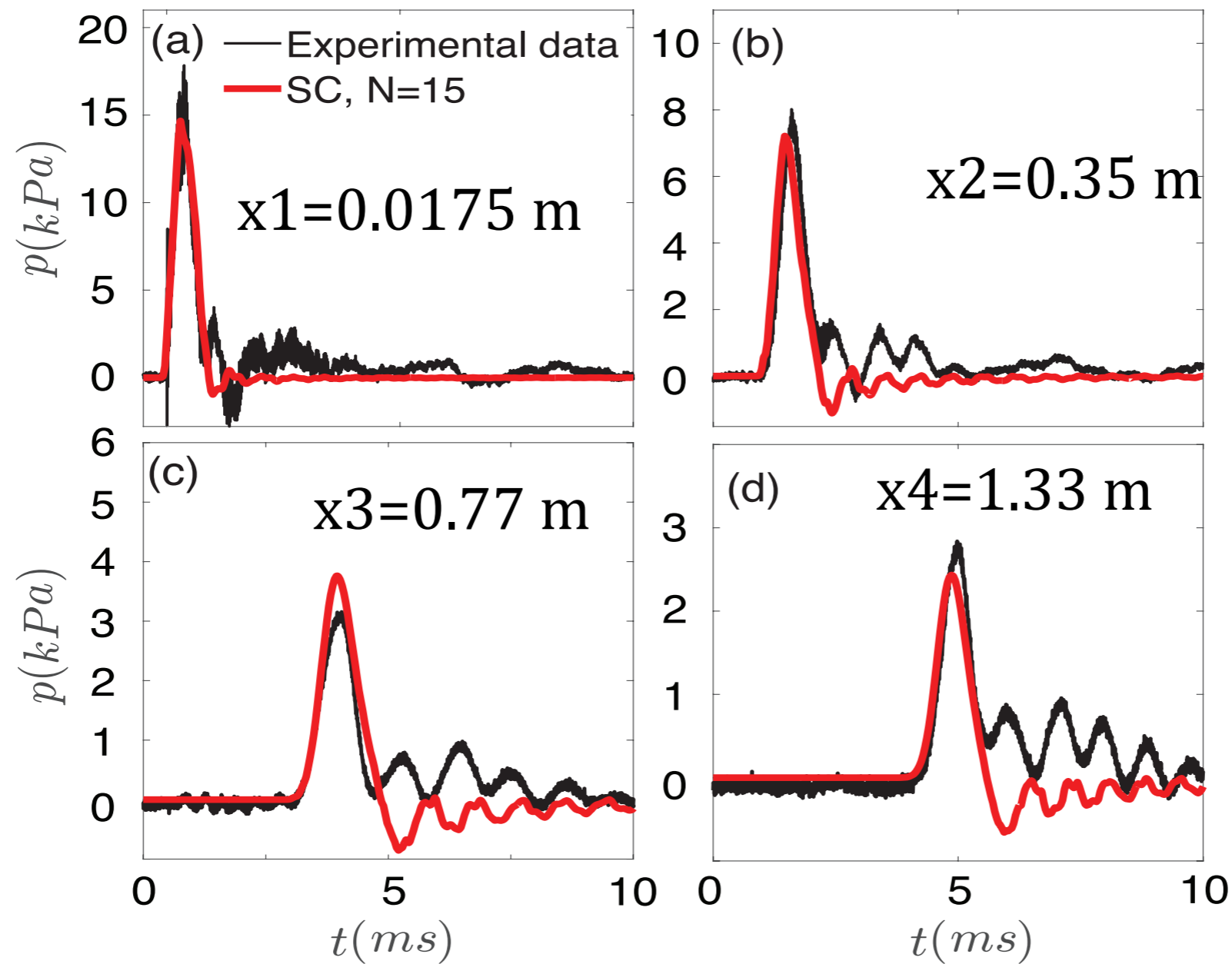
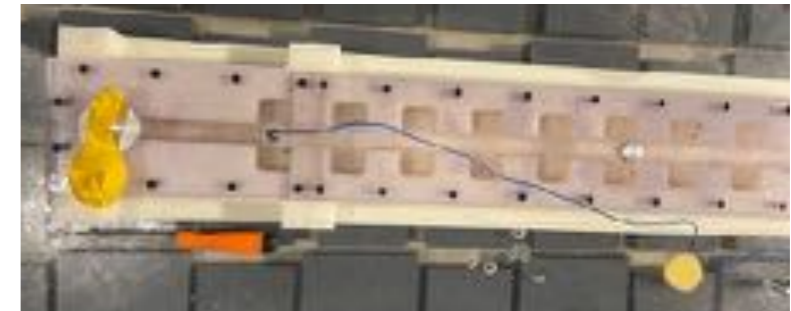
# Experiments



Balloon explosion



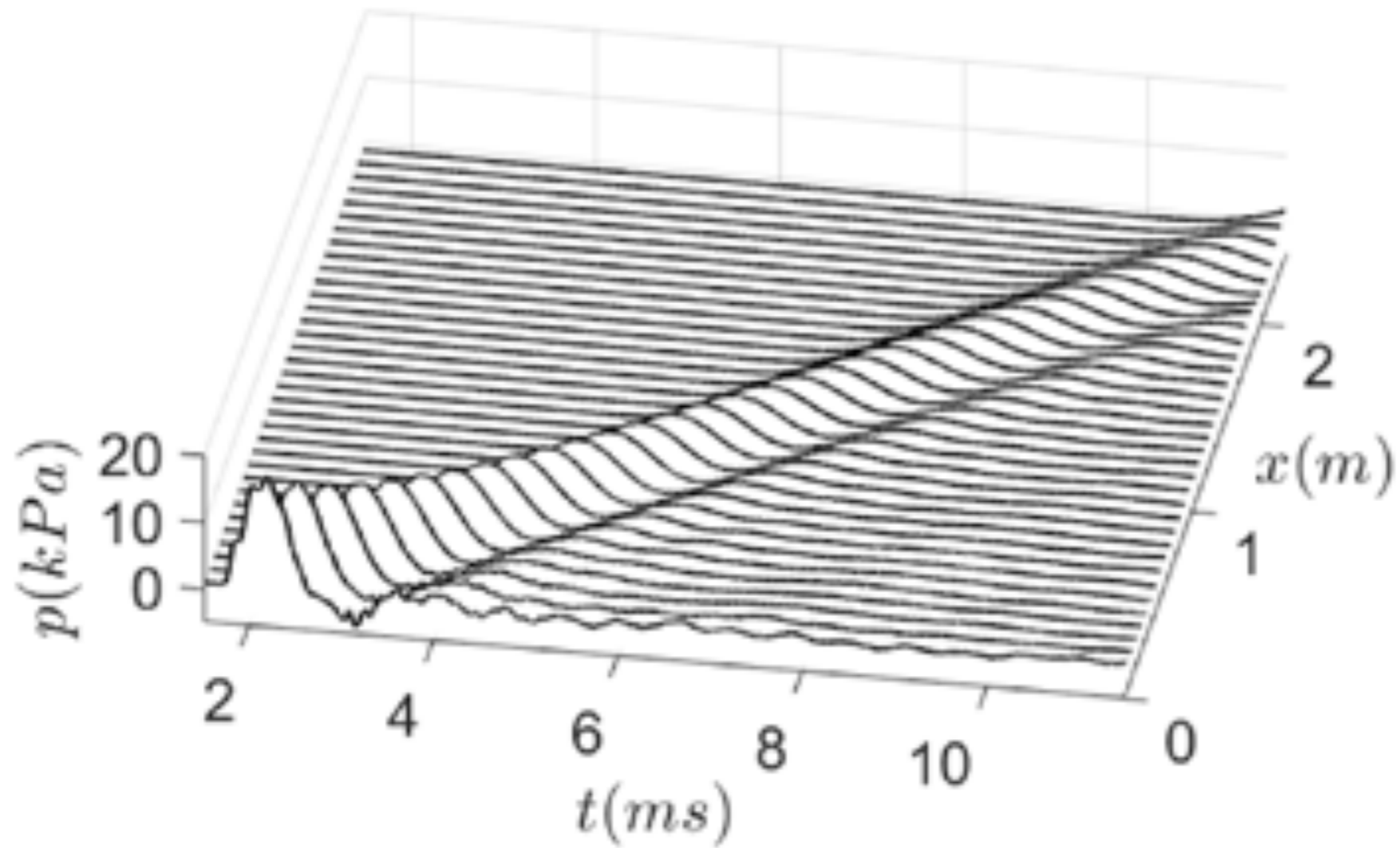
One of many realisations





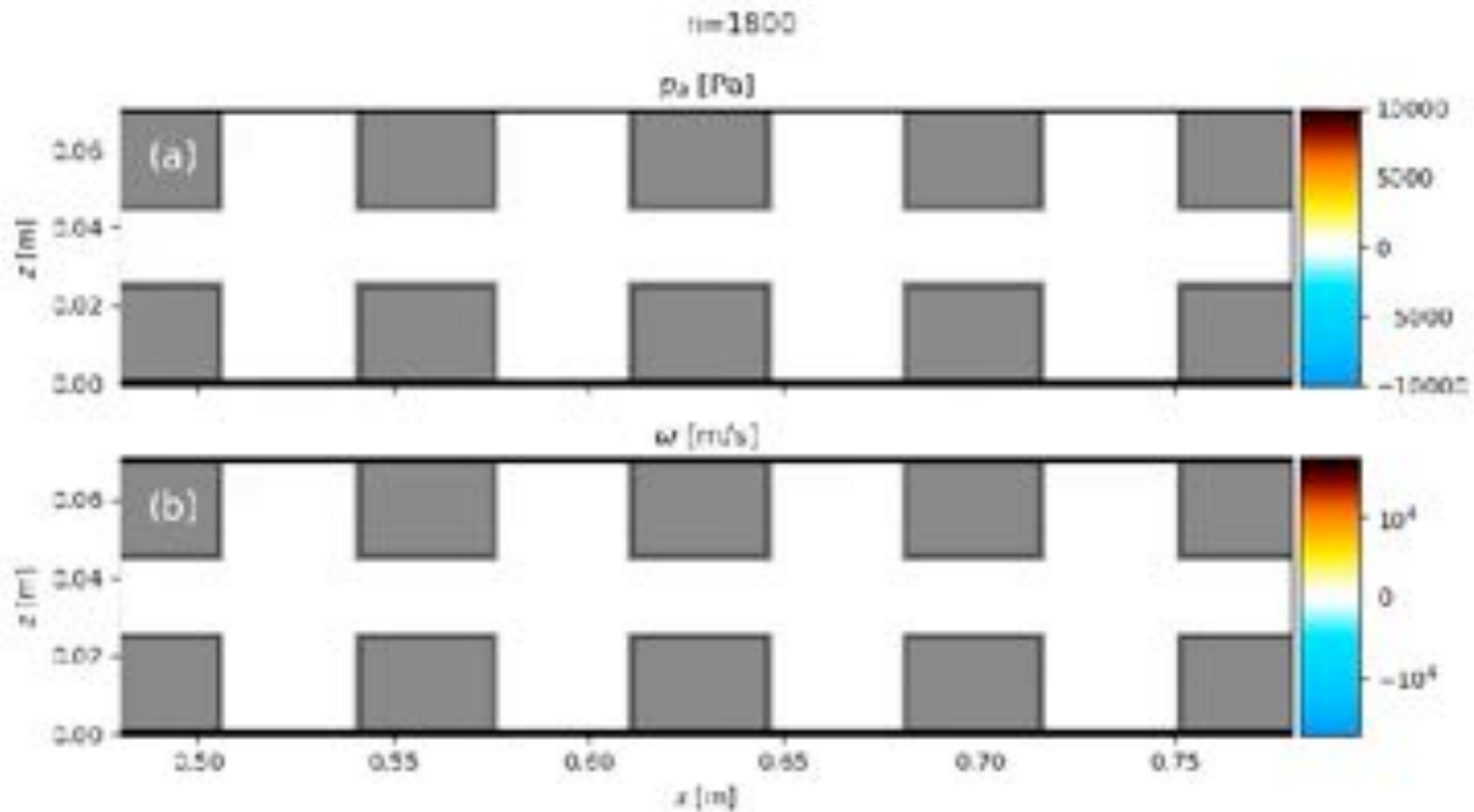
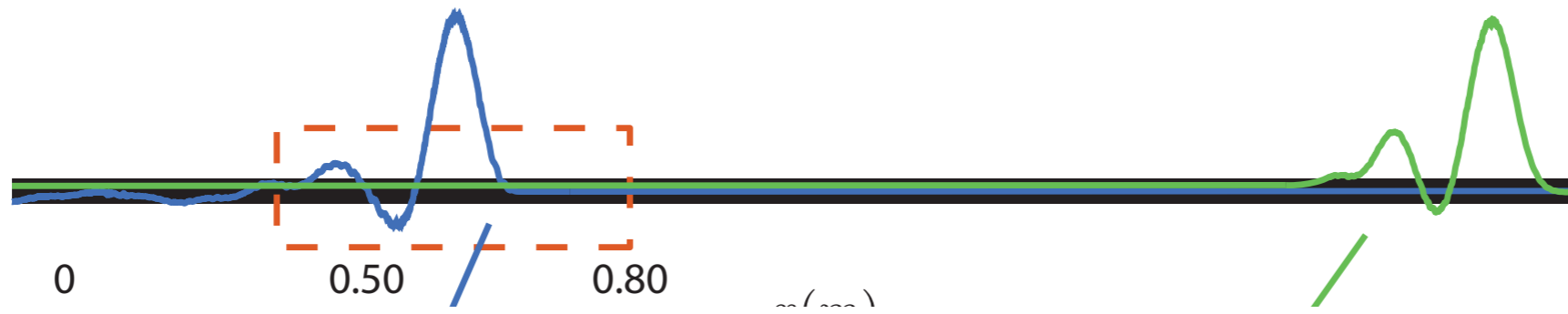
# Experiments and effect of losses

2D numerical simulations - soliton decay



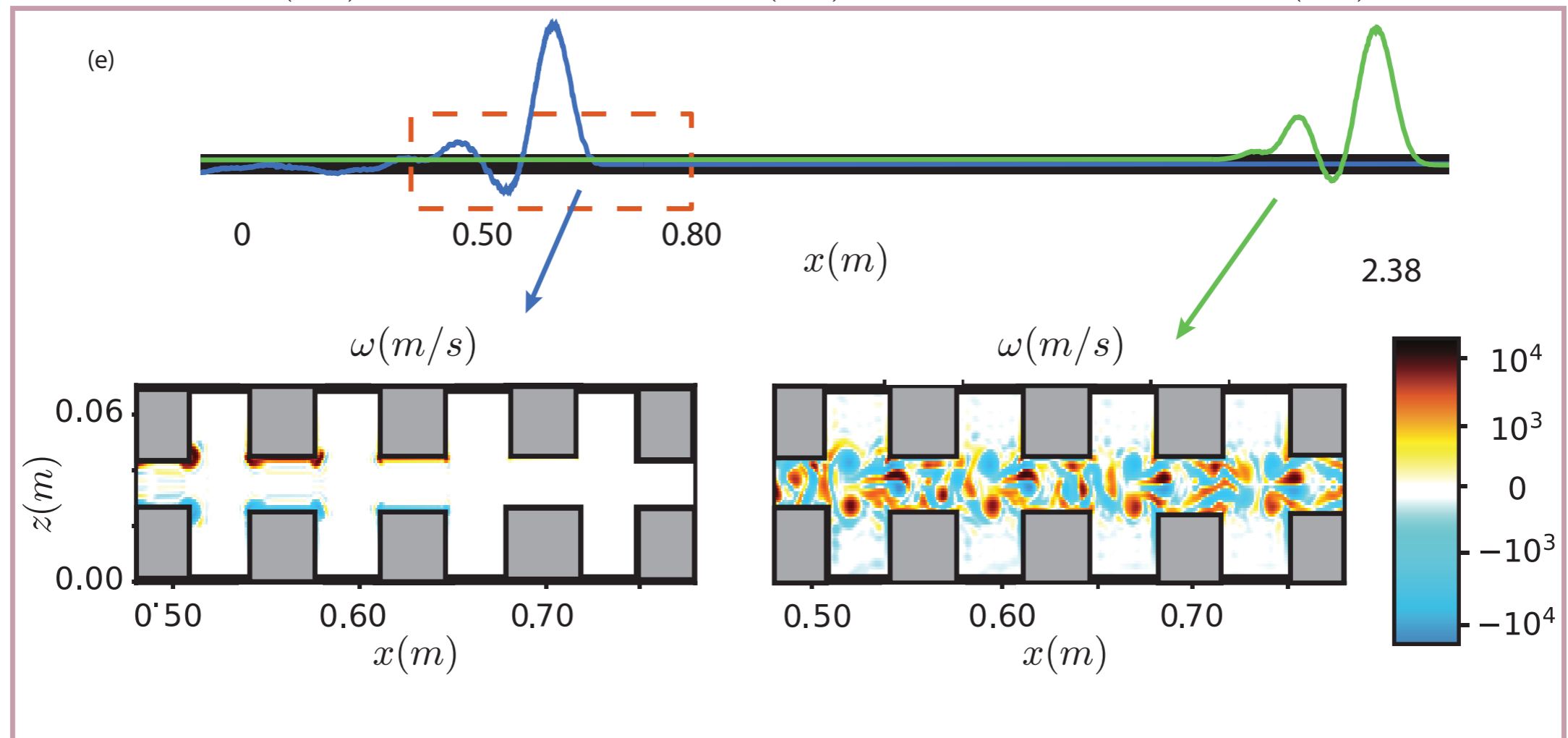
# Experiments effect of losses

2D numerical simulations



# Experiments and the effect of losses

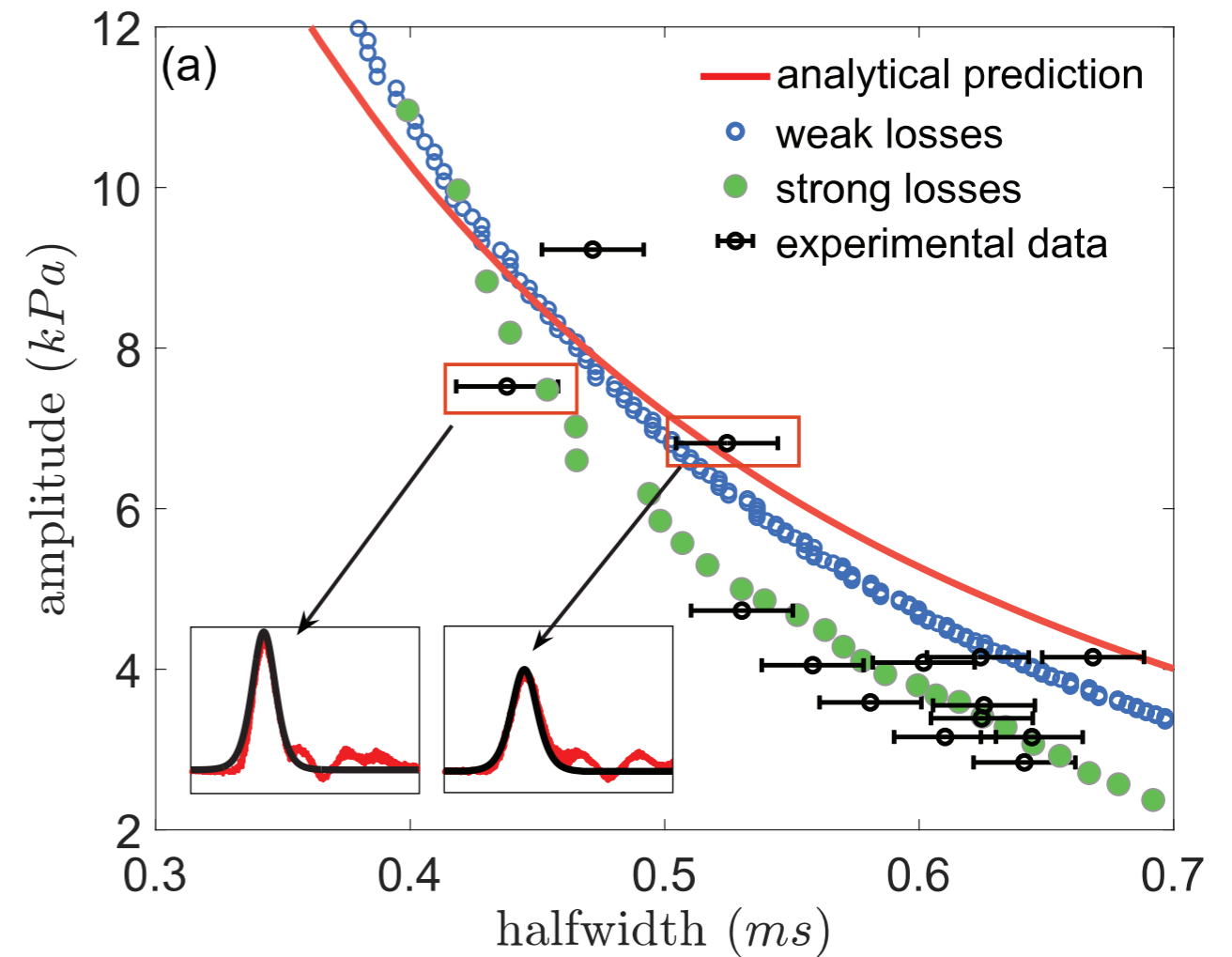
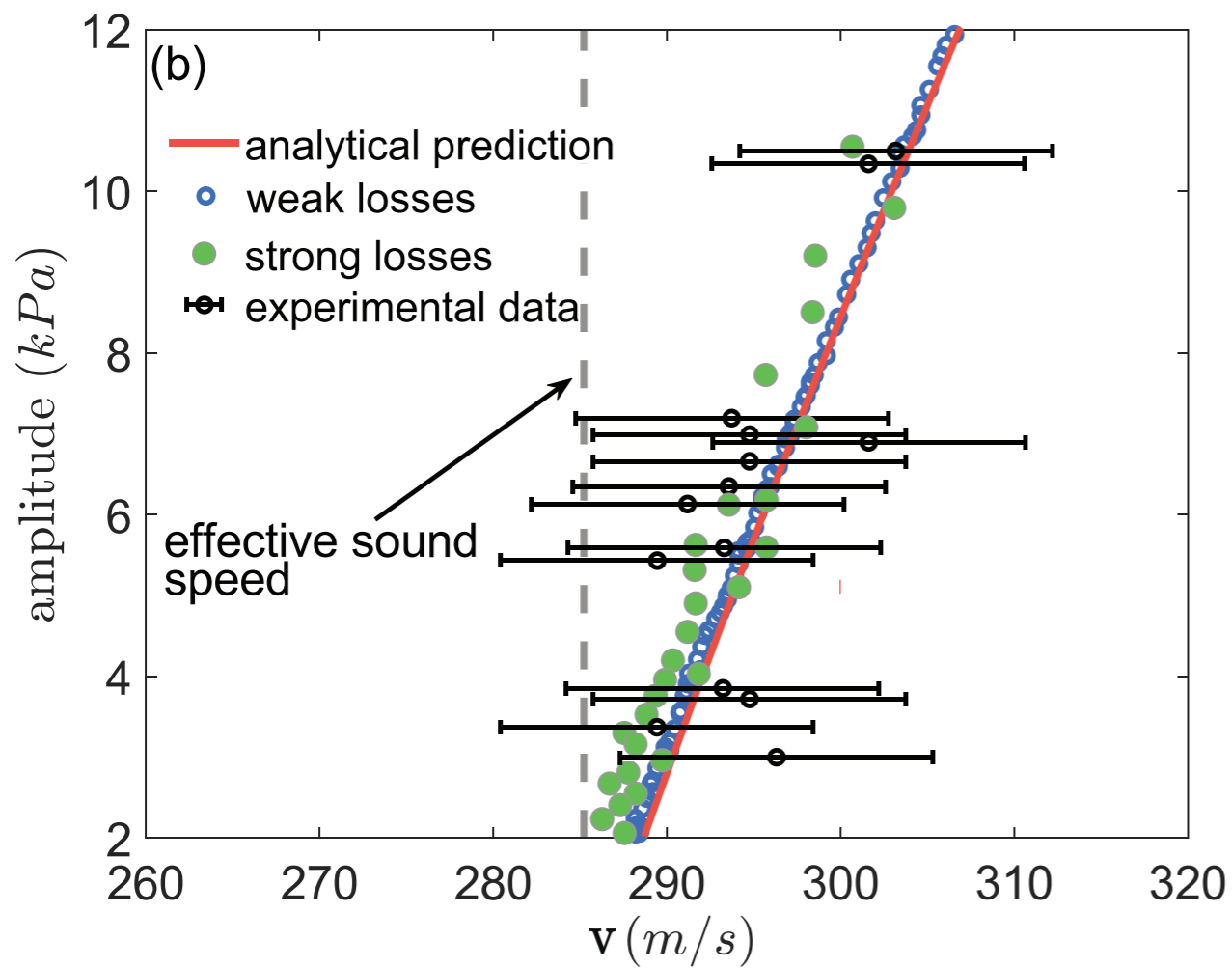
2D numerical simulations - soliton decay



# Experiments comparison with the soliton

## Comparison with theoretical prediction

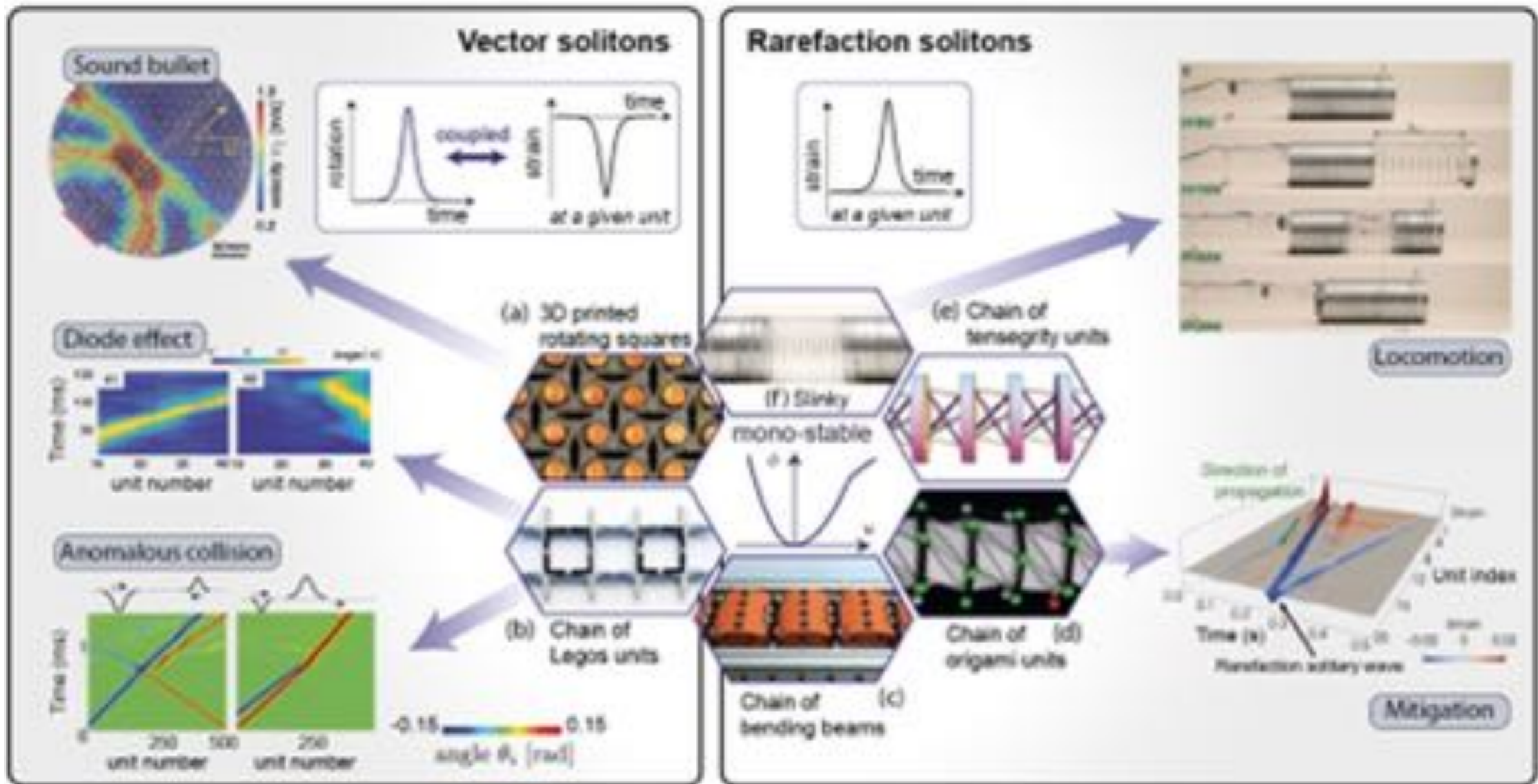
$$p(x, t) = A \operatorname{sech}^2(w(x - vt)) \quad A = \frac{3(\nu^2 - \tilde{c}^2)}{2b\nu^2}, \quad w = ((\nu^2 - \tilde{c}^2)/4(\beta_x + \beta_m\nu^2))^{1/2}$$



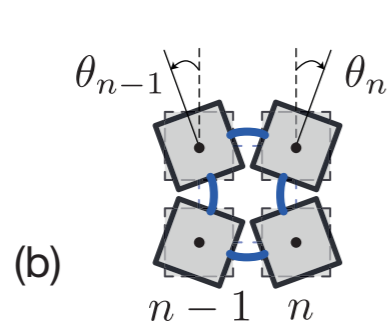
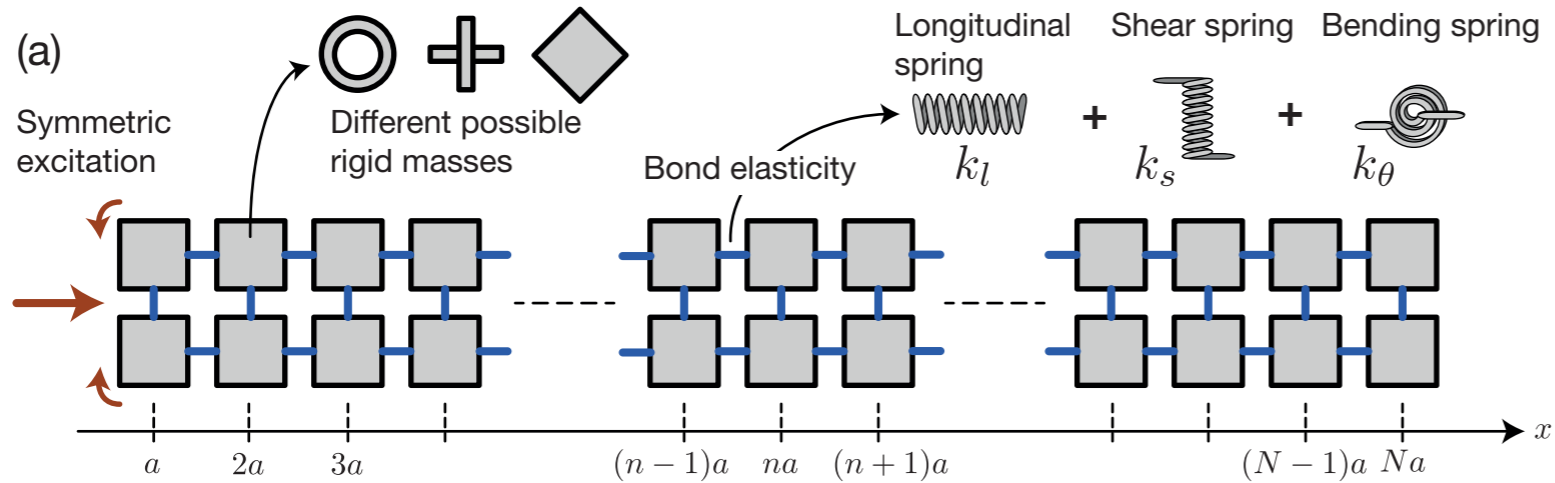
# Part 2: Modulation Instability in FlexEM

## Flexible Elastic Metamaterials

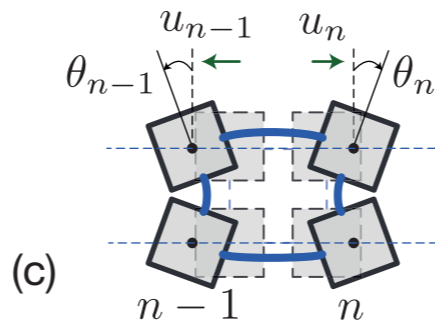
## Pulse excitations



# Part 2: Modulation Instability in FlexEM



Case (I): Rotation

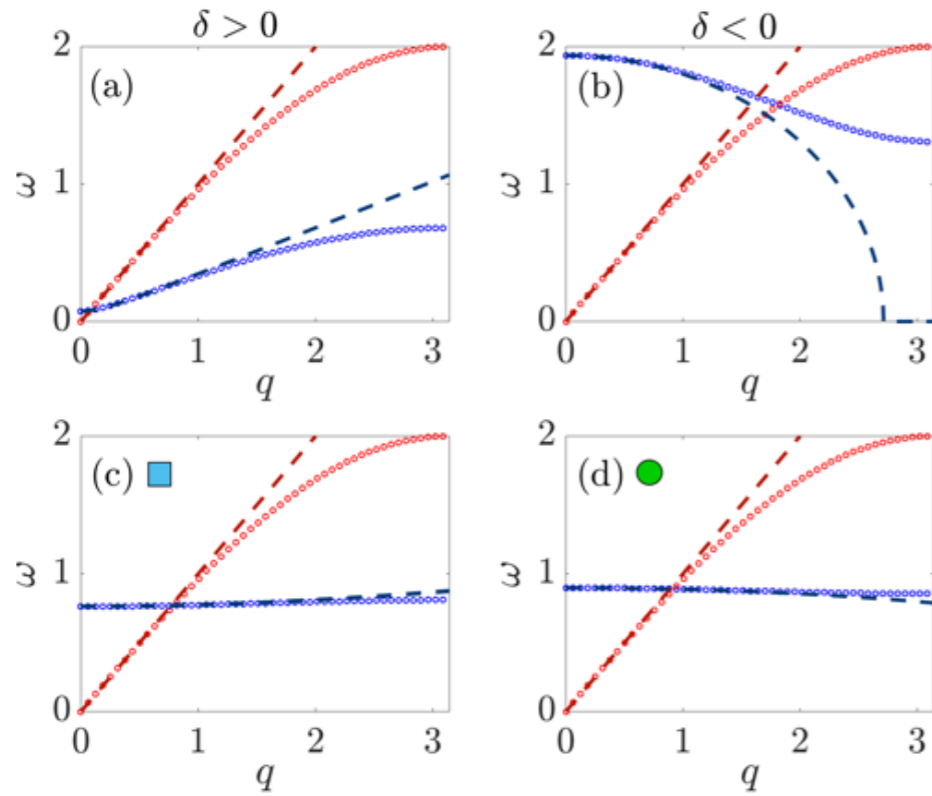


Case (II): Rotation + Displacement

$$\frac{\partial^2 U_n}{\partial T^2} = U_{n+1} - 2U_n + U_{n-1} - \frac{\cos \theta_{n+1} - \cos \theta_{n-1}}{2}$$

$$\frac{1}{\alpha^2} \frac{\partial^2 \theta_n}{\partial T^2} = -K_\theta (\theta_{n+1} + 4\theta_n + \theta_{n-1}) + K_s \cos \theta_n [\sin \theta_{n+1} + \sin \theta_{n-1} - 2 \sin \theta_n] - \sin \theta_n [2 (U_{n+1} - U_{n-1}) + 4 - 2 \cos \theta_n - \cos \theta_{n+1} - \cos \theta_{n-1}]$$

# Part 2: Modulation Instability in FlexEM

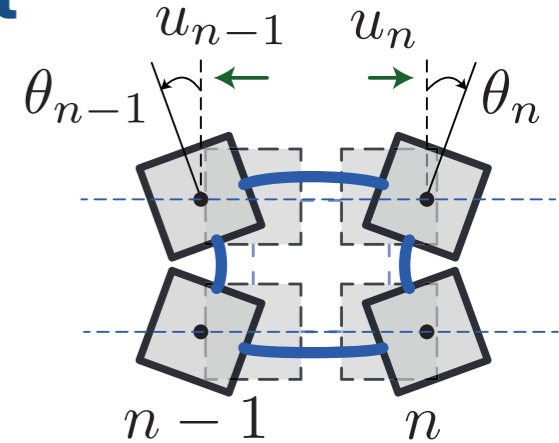


## Decoupled in the linear limit

$$\omega^{(1)} = 2 \sin\left(\frac{qa}{2}\right),$$

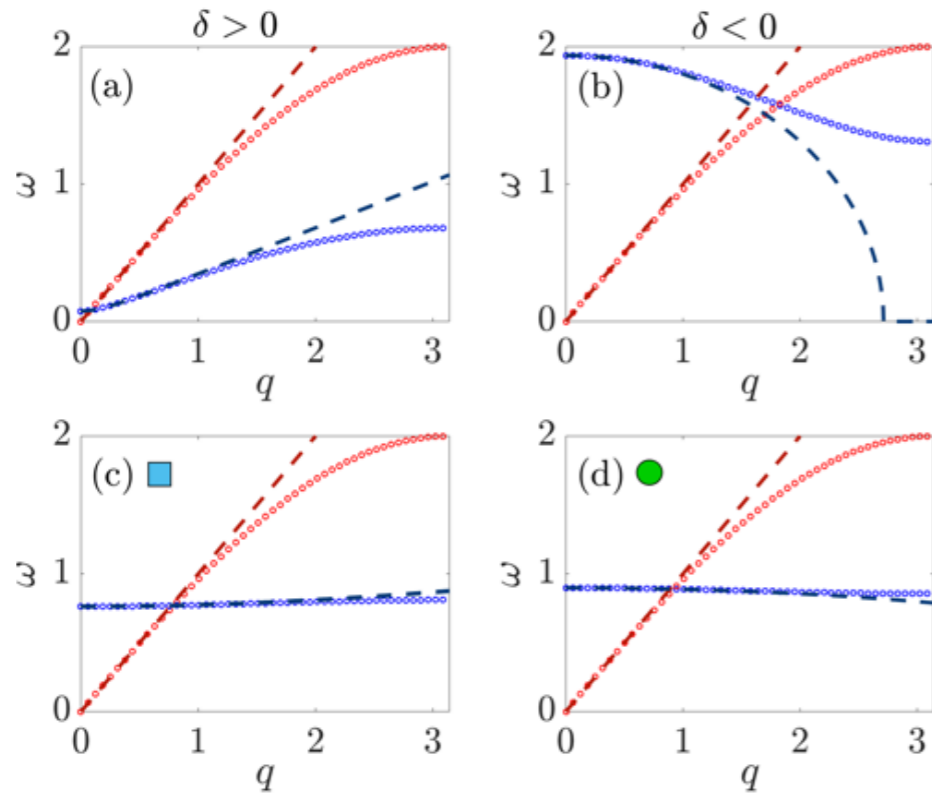
$$\omega^{(2)} = \pm \sqrt{4\alpha^2(K_s - K_\theta) \sin^2\left(\frac{qa}{2}\right) + 6\alpha^2 K_\theta}$$

$$\delta = K_s - K_\theta.$$



# Part 2: Modulation Instability in FlexEM

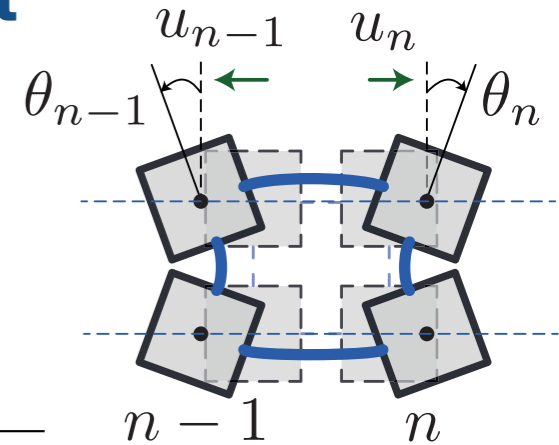
## Decoupled in the linear limit



$$\omega^{(1)} = 2 \sin\left(\frac{qa}{2}\right),$$

$$\omega^{(2)} = \pm \sqrt{4\alpha^2(K_s - K_\theta) \sin^2\left(\frac{qa}{2}\right) + 6\alpha^2 K_\theta}$$

$$\delta = K_s - K_\theta.$$



## Effective PDE At long wavelengths $\lambda \gg a$

$$\frac{\partial^2 U}{\partial T^2} = \frac{\partial^2 U}{\partial X^2} + \theta \frac{\partial \theta}{\partial X},$$

$$\frac{\partial^2 \theta}{\partial T^2} = C_1 \frac{\partial^2 \theta}{\partial X^2} - C_2 \theta - C_3 \theta^3 - C_4 \theta \frac{\partial U}{\partial X}$$



# Part 2: Modulation Instability in FlexEM

## At long wavelengths $\lambda \gg a$

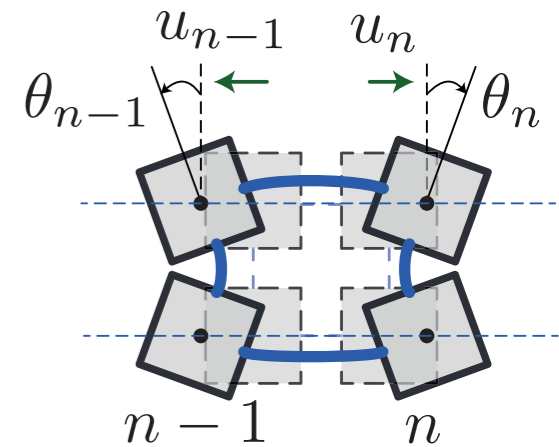
$$\frac{\partial^2 U}{\partial T^2} = \frac{\partial^2 U}{\partial X^2} + \theta \frac{\partial \theta}{\partial X},$$

$$\frac{\partial^2 \theta}{\partial T^2} = C_1 \frac{\partial^2 \theta}{\partial X^2} - C_2 \theta - C_3 \theta^3 - C_4 \theta \frac{\partial U}{\partial X}$$

## Use multiple scales analysis

$$U = \epsilon u_1 + \epsilon^2 u_2 + \epsilon^3 u_3 + \dots$$

$$\theta = \epsilon \theta_1 + \epsilon^2 \theta_2 + \epsilon^3 \theta_3 + \dots$$

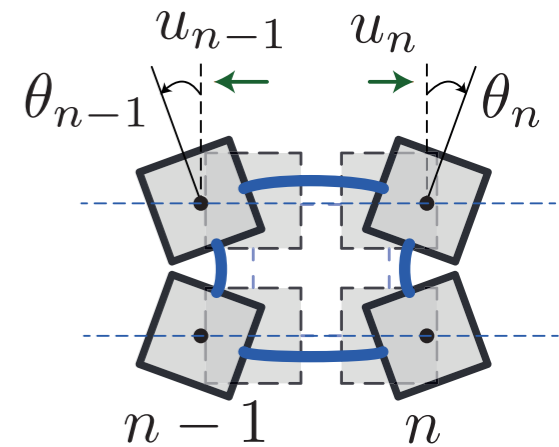


# Part 2: Modulation Instability in FlexEM

## At long wavelengths $\lambda \gg a$

$$\frac{\partial^2 U}{\partial T^2} = \frac{\partial^2 U}{\partial X^2} + \theta \frac{\partial \theta}{\partial X},$$

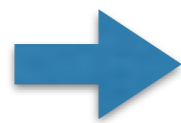
$$\frac{\partial^2 \theta}{\partial T^2} = C_1 \frac{\partial^2 \theta}{\partial X^2} - C_2 \theta - C_3 \theta^3 - C_4 \theta \frac{\partial U}{\partial X}$$



## Use multiple scales analysis

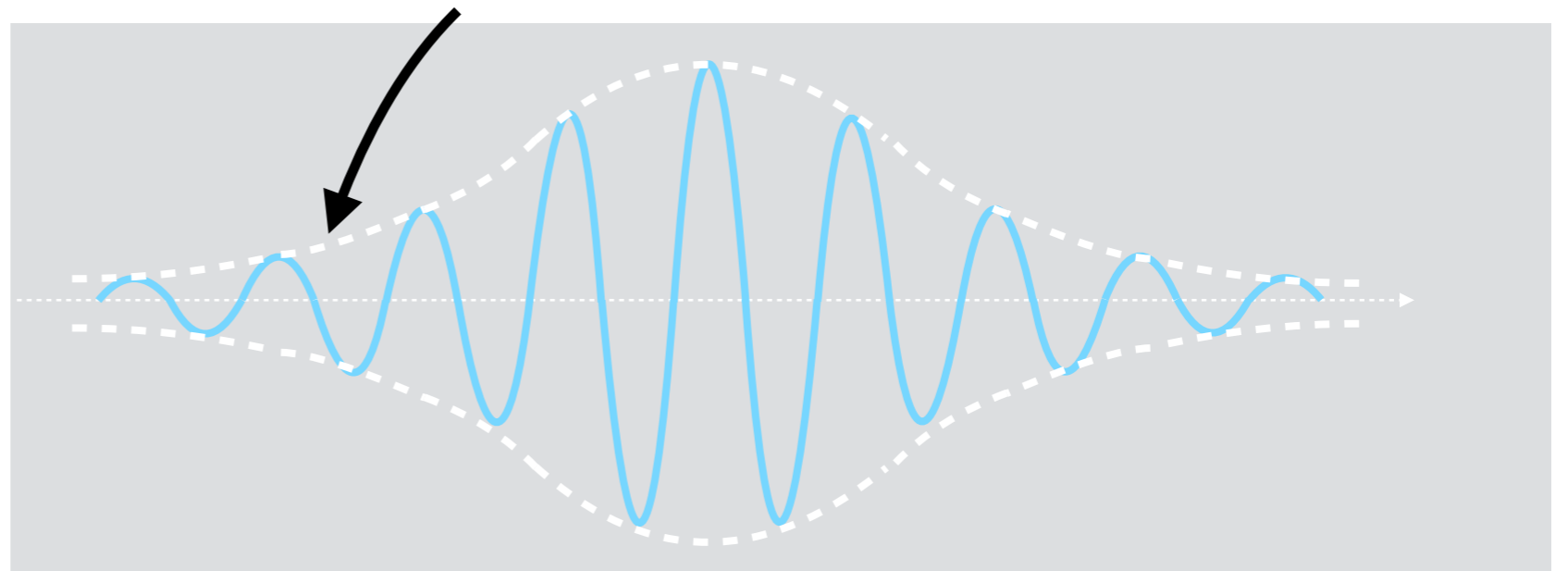
$$U = \epsilon u_1 + \epsilon^2 u_2 + \epsilon^3 u_3 + \dots$$

$$\theta = \epsilon \theta_1 + \epsilon^2 \theta_2 + \epsilon^3 \theta_3 + \dots$$



Larger rotations

$$\theta_1 = B(X_1, T_1, X_2, T_2, \dots) e^{i(kX_0 - \omega T_0)} + \text{c.c.},$$



# Part 2: Modulation Instability in FlexEM

## Nonlinear Schrödinger Equation for the envelope

$$\theta = B(X_1, T_1, X_2, T_2, \dots) e^{i(kX_0 - \omega T_0)} + \text{c.c.},$$

$$i \frac{\partial B}{\partial \tilde{\tau}_2} + \frac{1}{2} \frac{\partial^2 B}{\partial \xi_1^2} + g|B|^2 B = 0$$

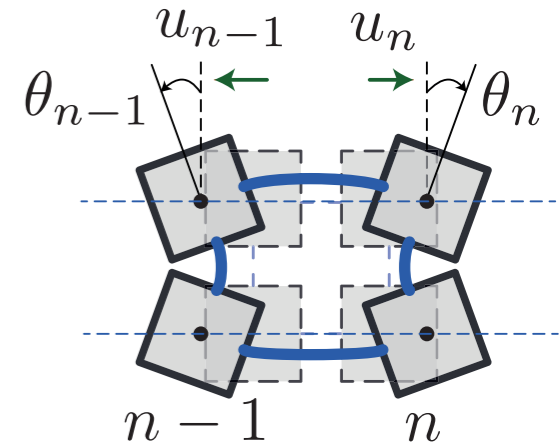
### Derive conditions for Modulational Instability

$$B(\xi_1, \tilde{\tau}_2) = (A_0 + b(\xi_1, \tilde{\tau}_2)) e^{i(k_0 \xi_1 - \omega_0 \tilde{\tau}_2 + \tilde{\theta}(\xi_1, \tilde{\tau}_2))}$$

$$b = f_1 e^{i(K\xi_1 - \Omega\tilde{\tau}_2)}, \quad \tilde{\theta} = f_2 e^{i(K\xi_1 - \Omega\tilde{\tau}_2)}$$

$$\Omega = Kk_0 \pm |K| \sqrt{\frac{K^2}{4} - gA_0^2}$$

If  $g > 0$  and  $K < |K_c| = 2A_0\sqrt{g}$



The perturbations grow with time

$$\Omega = \Omega_R \pm i\Omega_I$$

$$\Omega_I = |K|A_0 \sqrt{g - \frac{K^2}{4A_0^2}}$$

# Part 2: Modulation Instability in FlexEM

## Nonlinear Schrödinger Equation for the envelope

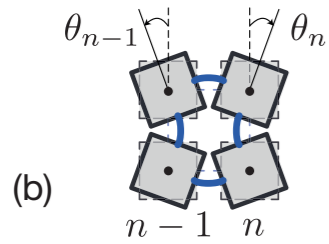
$$\theta = B(X_1, T_1, X_2, T_2, \dots) e^{i(kX_0 - \omega T_0)} + \text{c.c.},$$

$$i \frac{\partial B}{\partial \tilde{\tau}_2} + \frac{1}{2} \frac{\partial^2 B}{\partial \xi_1^2} + g |B|^2 B = 0$$

unstable if

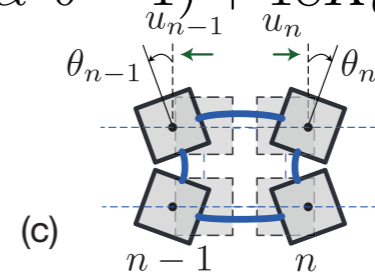
$$\Omega_I = |K| A_0 \sqrt{g - \frac{K^2}{4A_0^2}}$$

$$g = \frac{-3\alpha^2}{\delta\alpha^2 - v_g^2}$$

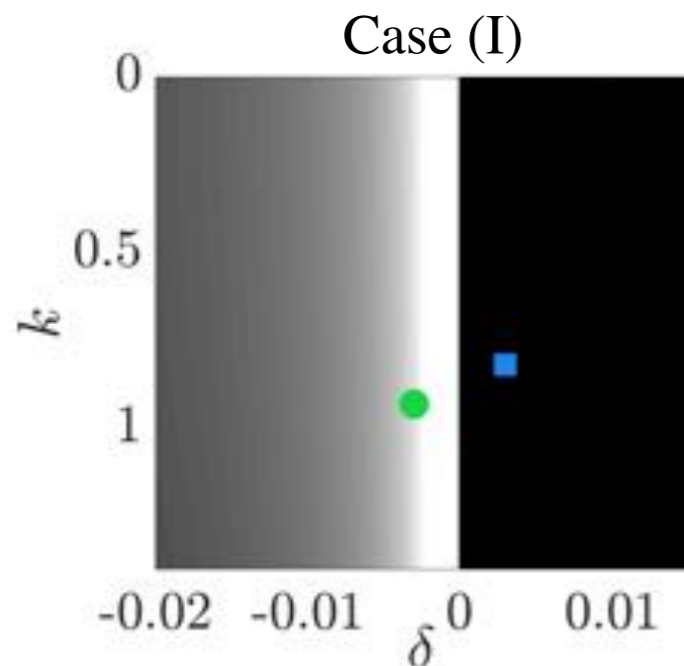


Case (I): Rotation

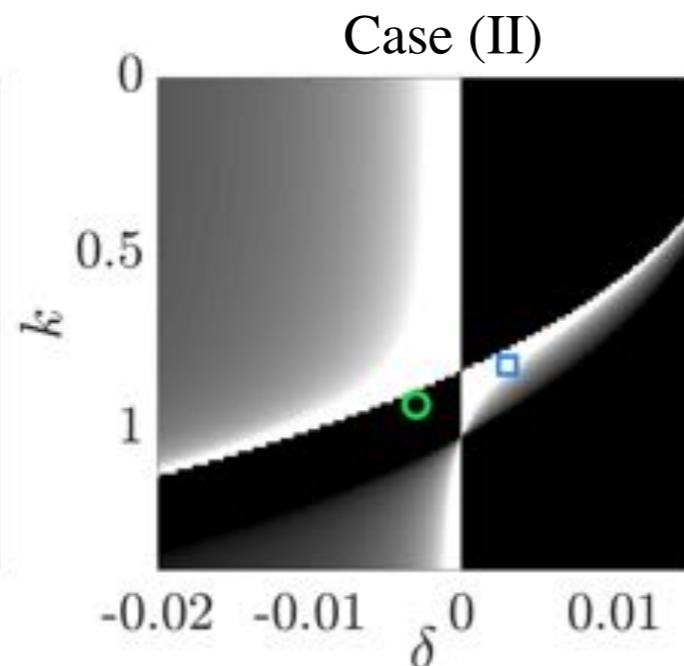
$$g = \frac{-3\alpha^2}{\delta\alpha^2 - v_g^2} \left( 1 + \frac{k^2}{3k^2 (\alpha^2 \delta - 1) + 18K_\theta \alpha^2} \right)$$



Case (II): Rotation + Displacement



Case (I)



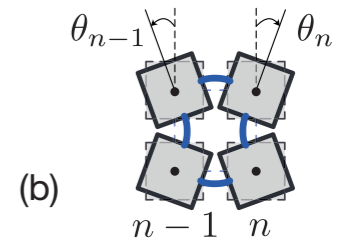
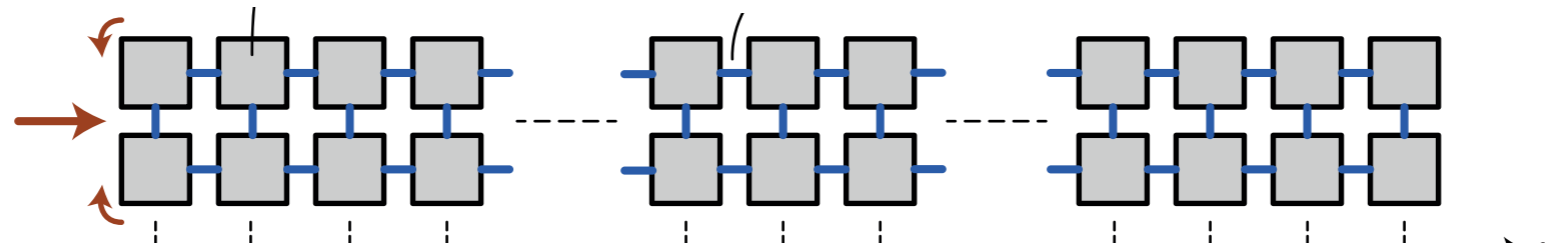
Case (II)

Unstable

Stable

# Part 2: Modulation Instability in FlexEM

Case (I)

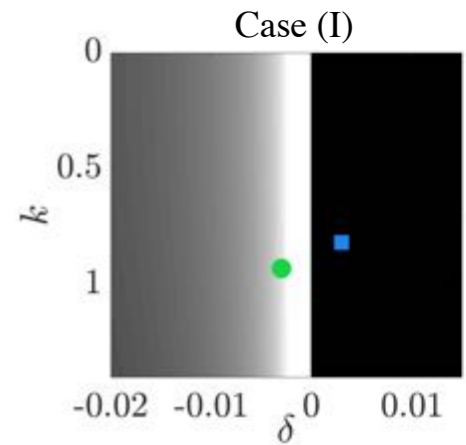
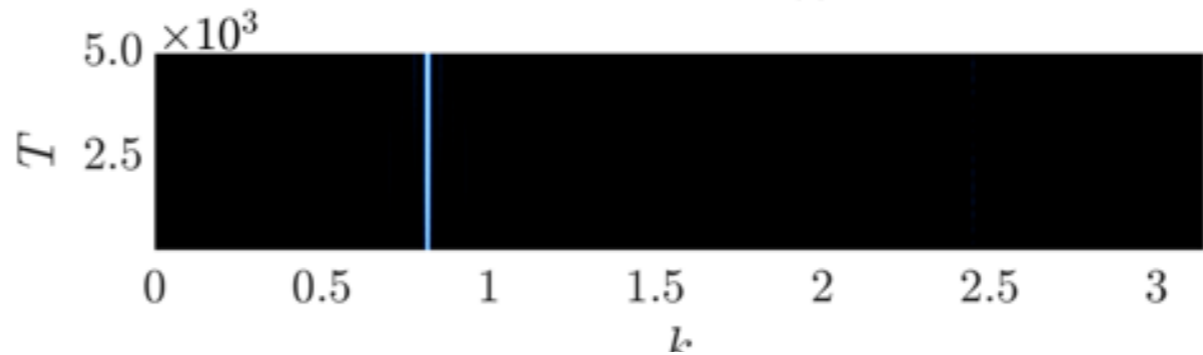
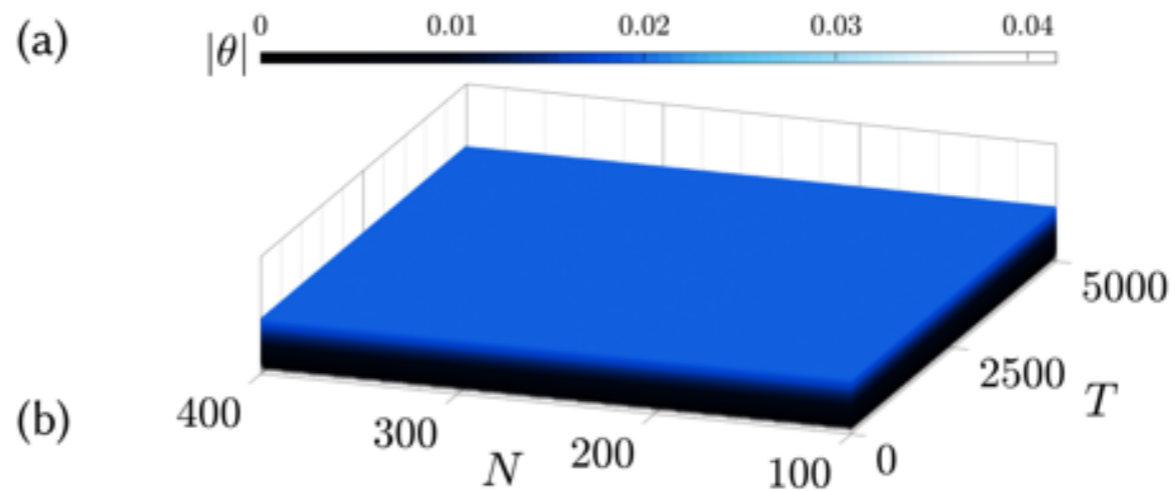


Case (I): Rotation

## I. C. Modulated plane wave

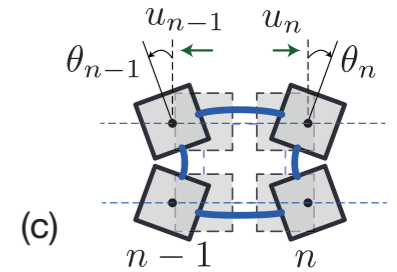
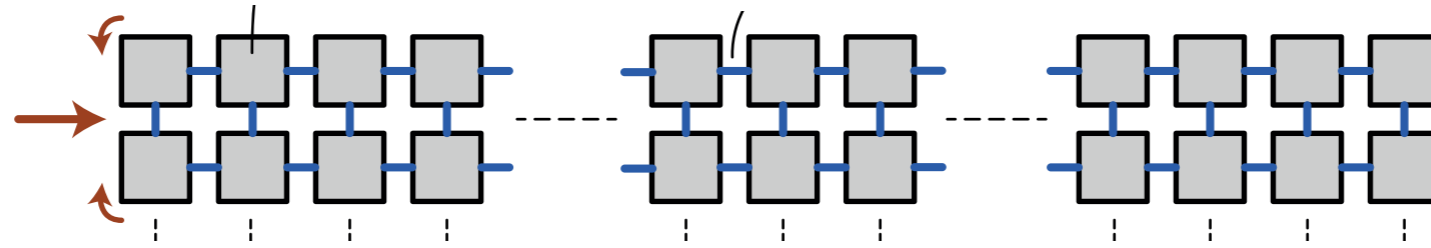
$$\theta(n, 0) = 2\epsilon(1 + b_0) \cos(kn),$$

$$\dot{\theta}(n, 0) = 2\epsilon\omega(k)(1 + b_0) \sin(kn)$$



# Part 2: Modulation Instability in FlexEM

Case (II)



Case (II): Rotation + Displacement

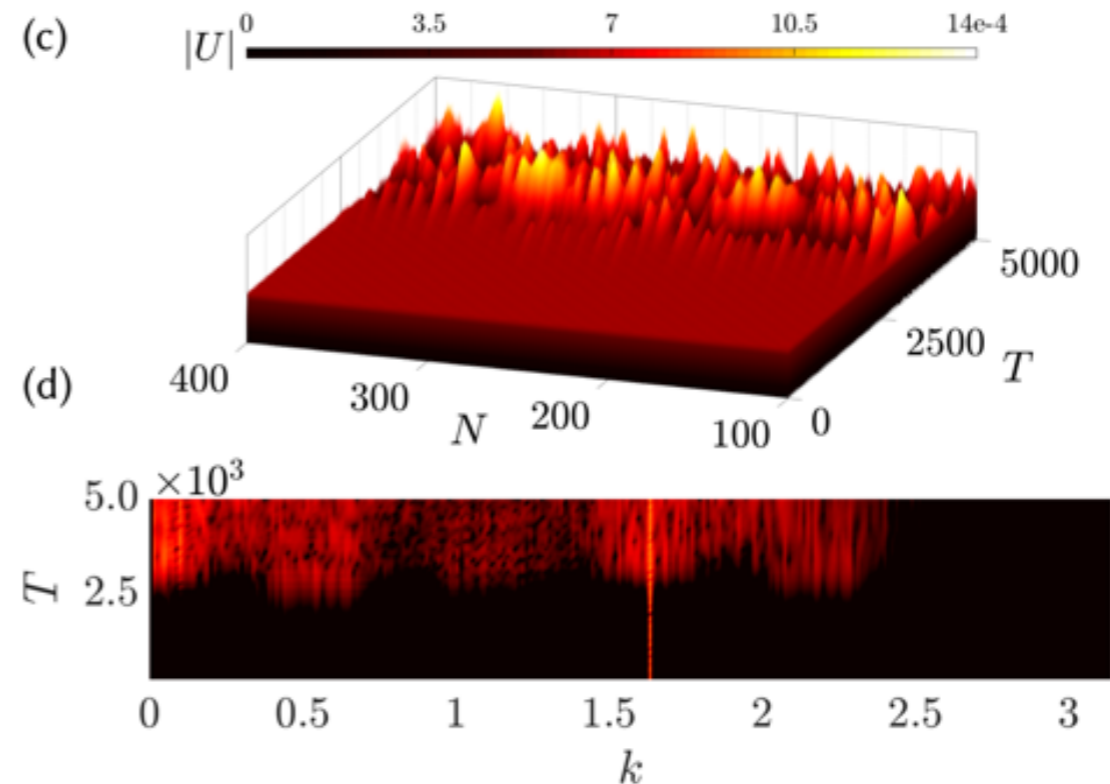
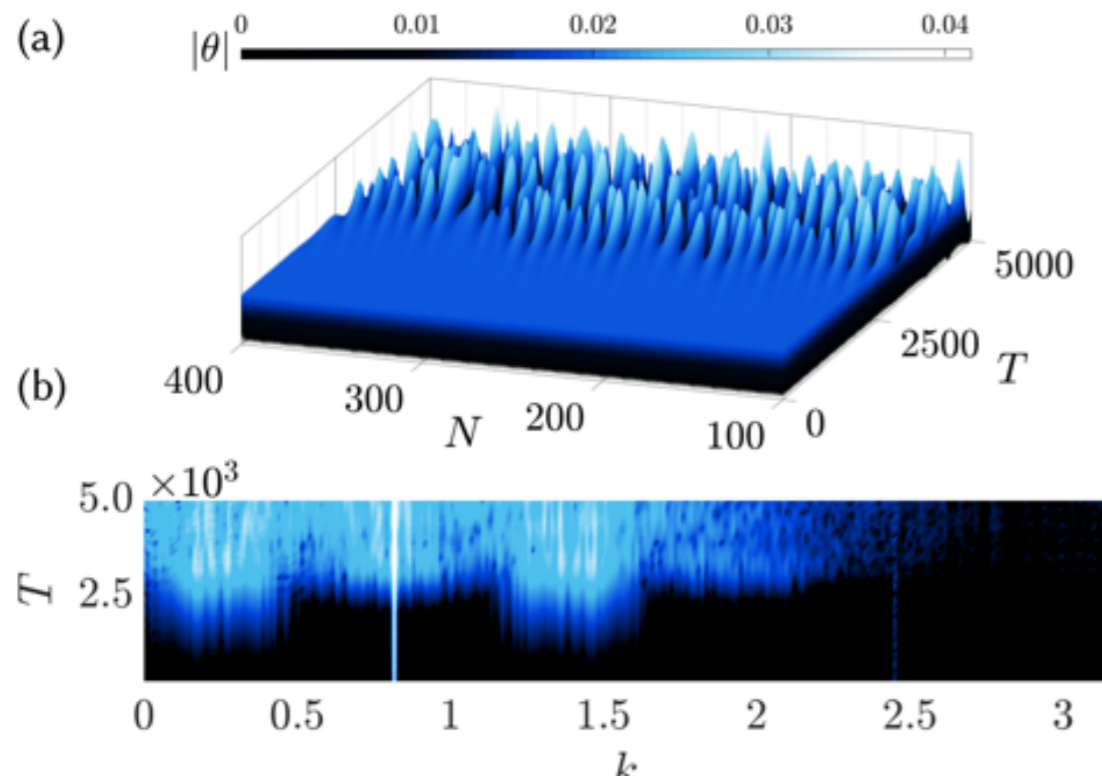
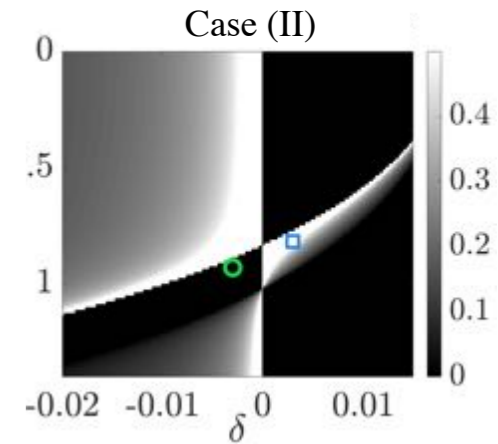
## I. C. Modulated plane wave

**Coupling induces the instability**

new wavenumbers  
localised structures appear in the long time

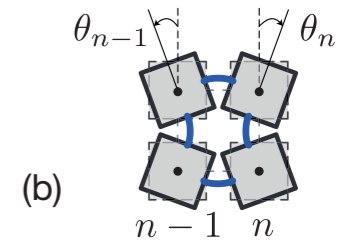
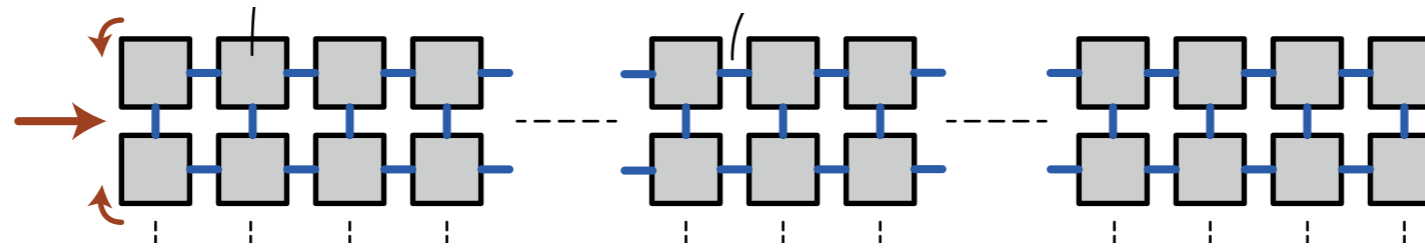
$$\theta(n, 0) = 2\epsilon(1 + b_0) \cos(kn),$$

$$\dot{\theta}(n, 0) = 2\epsilon\omega(k)(1 + b_0) \sin(kn)$$



# Part 2: Modulation Instability in FlexEM

Case (I)



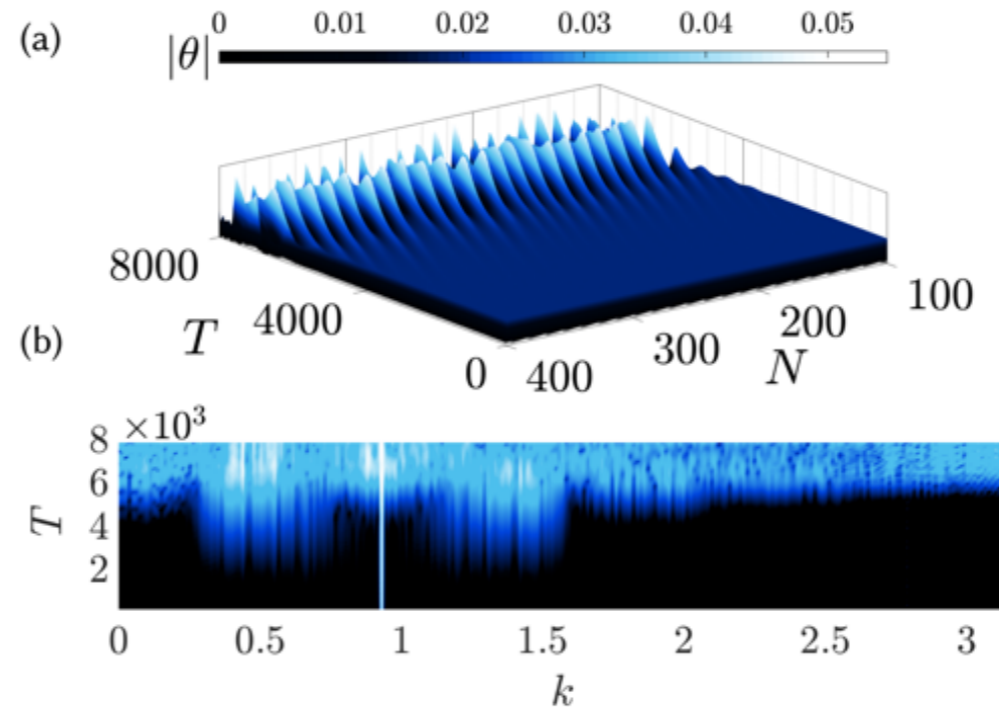
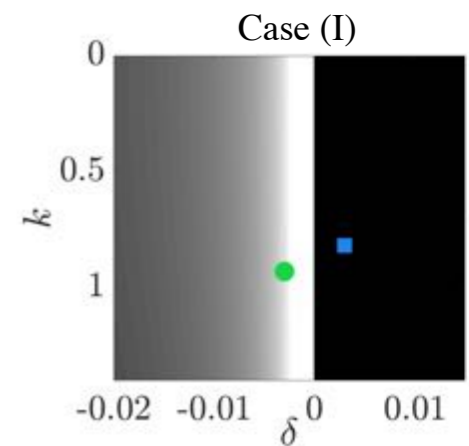
Case (I): Rotation

## I. C. Modulated plane wave

$$\theta(n, 0) = 2\epsilon(1 + b_0) \cos(kn),$$

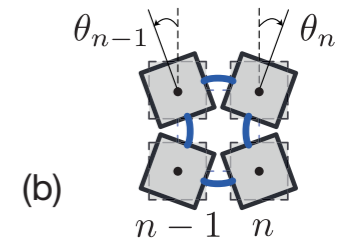
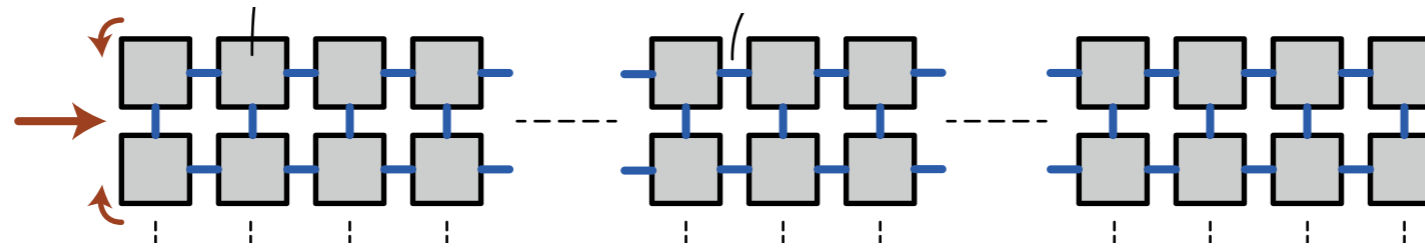
$$\dot{\theta}(n, 0) = 2\epsilon\omega(k)(1 + b_0) \sin(kn)$$

**Rotations alone are unstable**



# Part 2: Modulation Instability in FlexEM

Case (I)



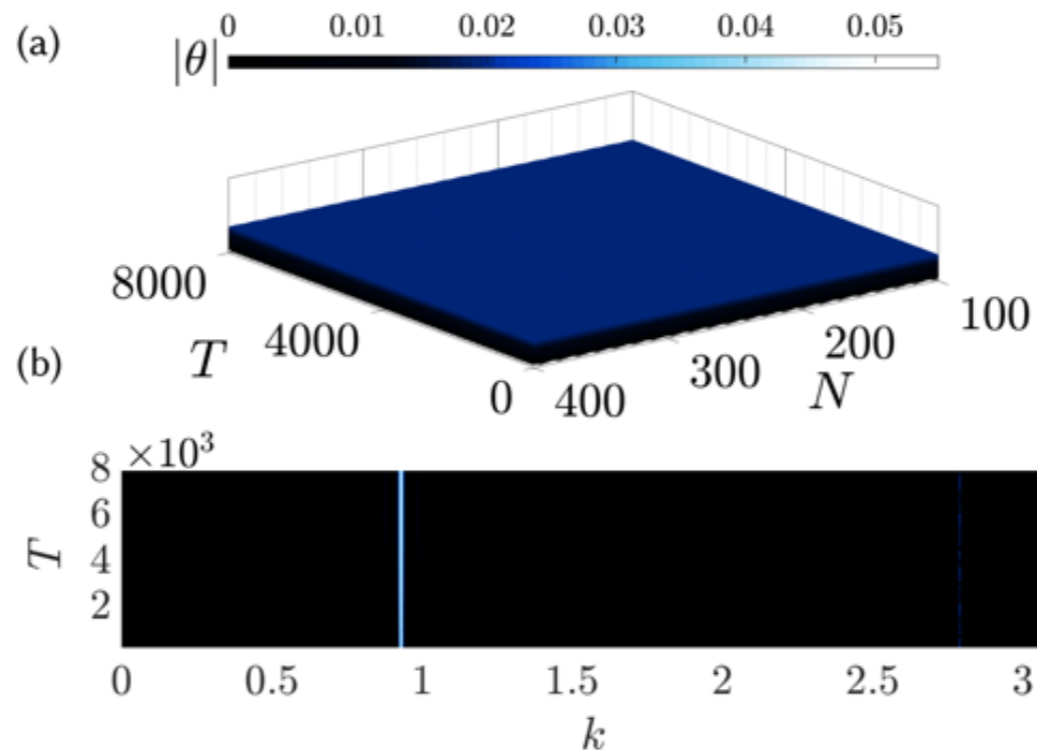
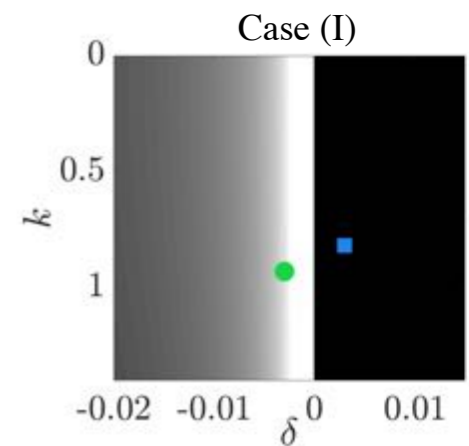
Case (I): Rotation

I. C. Modulated plane wave

$$\theta(n, 0) = 2\epsilon(1 + b_0) \cos(kn),$$

$$\dot{\theta}(n, 0) = 2\epsilon\omega(k)(1 + b_0) \sin(kn)$$

**Coupling stabilises the system**

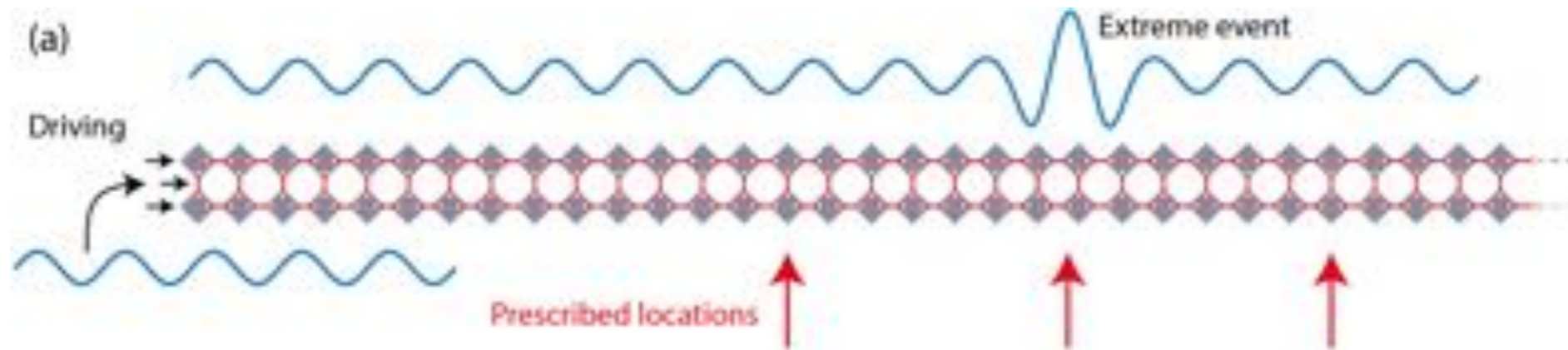




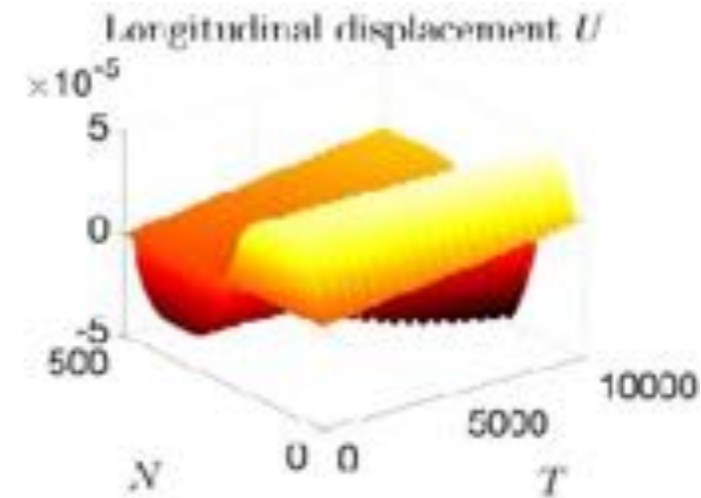
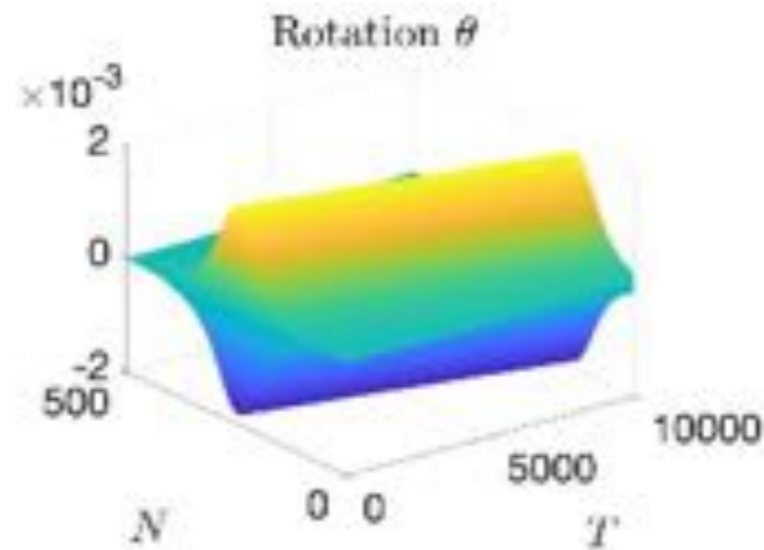
# Part 2: Modulation Instability in FlexEM

## Main perspectives

1. Instability in smaller structures, driven damped problem



2. Formation of localized nonlinear waves and rogue waves



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## Post-doc positions

*Experiments with nonlinear waves in flexible elastic metamaterials*

ANR project **ExFLEM** : collaboration LAUM (Le Mans), supméca (Paris)

*Absorption of nonlinear waves using passive and active scatterers*

ERC - StG project **NASA**: LAUM (Le Mans)